Analysis of Pre-Flight Modulator Voltage Calibration Data for the Voyager Plasma Science Experiment

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CSR-TR-88-1

This work supported in part under:

- 1) NASA Contract 957781
- 2) NAGW-1209

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CSR-TR-88-1

April, 1988

1. Introduction

The digitized readout (DN = data number) of the low-voltage signal (MV) which is proportional to the potential (V) on the high-voltage modulator grids, is a part of the routine calibration sequence on the Voyager Plasma Science (PLS) experiment. Theoretically, in producing the modulator voltage, the voltage is stepped through one decade from 60 to 600 volts and then through the same steps with a multiplication factor of 10 to sweep from 600 to 6000 volts. To this voltage is added an offset of -50 volts.

The voltage monitors measure a voltage between 0.1 and 10 volts (a constant fraction of the voltage swept) which is then input into the fast A/D converter. This voltage is converted to a binary number from which the highest order bit is discarded. Thus, for MV sweeping from 0.1 to 1.0, a number between 0 and 255 is returned; for MV sweeping from 1.0 to 10 volts, again, a number between 0 and 255 is returned. To know which decade is being read out, one must either rely on the "proper sequence" or an "educated guess."

For more information on MVM Interpretation, see Voyager Memorandum #161 by R. L. McNutt, Jr. (attached).

2. An Outline of the PLS Calibration Data Analysis

The PLS Modulator Calibration (MVM) Data Analysis was undertaken in order to check the correctness of the fast A/D converter formulas that connect low-voltage monitor signals (MV) with digital outputs (DN), to determine the proportionality constants between the actual modulator grid potential (V) and the monitor voltage (MV), and to establish an algorithm to link the digitized readouts (DN) with the actual grid potential (V). The data used for the DN-MV analysis were from the calibration tests for the PLS-Prototype run at MIT CSR (included as Appendix A of Voyager Memo #161). The MV-V analysis used the results of the power supply tests, made by Matrix Research and Development Corp. for both PLS instruments to be flown on the Voyager 1 and Voyager 2 spacecraft (in the further text referred to as "test results"). The Matrix data was obtained between 11/11/76 and 11/15/76 for "Flite 1," and between 12/21/76 and 12/27/76 for "Flite 2." Drawings containing this data are labeled "M.J.S. Power Supply" (there are no drawing numbers). These are stored in the filing cabinet next to the outer wall, second drawer from the top in N52-367. Note that there is some potential confusion about which unit is which: if Flite 1 is SN002, then it is the instrument actually flown on Voyager 1. SN002 was put on Voyager 1 and SN003 which was supposed to have gone on Voyager 2 was not flown. When these data were taken, Flite 2 probably referred to SN003 which has remained at M.I.T. as the flight spare. SN001 was actually flown on Voyager 2.

All calibration tests and power supply tests were entered into a sequence of files. The method that was used in both analyses, i.e., DN-MV and MV-V, is an improved version of a least squares fit algorithm, implemented in several FORTRAN 77 programs (see, for example section 14.2 of Numerical Recipes: The Art of Scientific Computing, Press, W. H., B. P. Flannery, S. A. Teukolsky, and W. T. Vetterling, Cambridge University Press, New York, 1986).

3. Description of the Files

All of the files related to the investigation can presently be found on the directory /usr4/ojn. The file suffixes have the following meanings:

```
.dat ....... data files
.mon ...... mongo source code files
.f ...... FORTRAN 77 source code files
```

The DN-MV test data and mongo files have filenames of the form:

```
p[ mode ][ mvr # ].[ suffix ]
```

The MV-V test data and mongo files have filenames of the form:

```
f[ flite # ]-[ temperature ]-[ mode ].[ suffix ]
```

where:

```
mvr # = 1 if 0.1 \le MV \le 1.0
mvr # = 2 if 1.0 \le MV \le 10

flite # = 1 for Voyager 1 PLS Instrument
flite # = 2 for Voyager 2 PLS Instrument

temperature = 5 for Temp = -5°C

temperature = 10 for Temp = 10°C

temperature = r for Temp = room-temp

temperature = 30 for Temp = 30°C

temperature = 40 for Temp = 40°C
```

(The temperature is that to which the instrument was exposed during the test.)

```
mode = 1 for the L-mode
mode = m for the M-mode
mode = e1 for the E1-mode
mode = e2 for the E2-mode
```

suffix = dat if the file is a data file suffix = mon if the file is a mongo source code

Note that there are no files of the form f2-30-[mode].[suffix] due to lack of this information.

The files of the form:

tl[mvr #].f and tl[mvr #].dat

are FORTRAN 77 source code and output data files produced by their corresponding source code programs which make/contain the data from the theoretical fast A/D formulas for MV-DN conversion.

The FORTRAN 77 source code files that actually perform the analysis are:

dns-code.f DN-MV analysis mvs-code.f MV-V analysis

mvs-tc-code.f MV-V analysis combining the data files

that differ only by temperature

These source code files use the following driver files:

dns-driver.dat mvs-driver.dat mvs-tc-driver.dat

The analysis generates the following files:

dns-output.dat DN-MV analysis results vs-output.dat MV-V analysis results

mvs-tc-out.dat MV-V temperature-combined analysis results

4. Data File Organization

All data files are organized as matrices of numbers and/or strings. Their row structure is as follows:

p[mode][mvr #].dat and tl[mvr #].dat:

dn mv

where: dn are the data numbers

mv are the corresponding monitor voltages

f[flight #]-[temperature]-[mode].dat:

channel# hvdcout mvu mvl vl vu
where: channel# is the channel number
hvdcout is the dc high voltage output
mvl/mvu are the monitor low voltages at the
lower/upper channel edge
vl/vu are the actual grid potentials corresponding
to the mvl/mvu

dns-driver.dat:

filename mvr[mvr #] lines#

where: filename is the name of a file.

mvr[mvr #] is a character string that can be either

mvr1 or mvr2 depending on what range the value

of MV belongs to.

lines# is the number of lines in the file.

mvs-driver.dat:

filename startline-1 endline-1 startline-2 endline-2

where: startline-[chr #]/endline-[chr #] are the starting/ending line numbers for parts of the f[]-[]-[].dat data files that correspond to different channel ranges as follows:

chr # = 1 if $0 \le \text{channel} \# \le 7$ and mode = L or E2 $0 \le \text{channel} \# \le 63$ and mode = M all channels and mode = E1 chr # = 2 if $8 \le \text{channel} \# \le 15$ and mode = L or E2 $64 \le \text{channel} \# \le 127 \text{ and } \mod = M$

mvs-tc-driver.dat: (Note: this file is a single-column file.)

mfilename#1

filename#1.1

filename#1.2

*

mfilename#2

filename#2.1

where: mfilename#[integer1] is a character string of the form:

f[flite #]-[mode].dat which is found in the mvs-tc-output.dat file and labels the analysis results obtained by combining groups of f[]-[]-[].dat files that differ only by temperature.

filename#[integer1].[integer2] are the filenames of the f[]-[].dat data files that were combined.

dns-output.dat:

filename mvr[mvr #] c1 c2 sqd pairs#

where:

filename is the name of a file that labels the information obtained by its analysis.

mvr[mvr #] is as explained under dns-driver.dat. c_1 , c_2 are constants in the presumed function that fits the data.

sqd is the square deviation of the function. pairs# is the number of analyzed data pairs.

mys-output.dat:

filename chr[chr #] mvx-vx a b sqd siga sigb cov pairs#

where:

chr[chr #] is a character string that can be either chr1 or chr2. chr # has a meaning as explained under mvs-driver.dat.

mvx-vx is a character string that can be either
mvl-vl or mvu-vu. It specifies what monitor
voltages were analyzed - those at the upper or

at the lower channel edge.

a, b are constants in the presumed function that fits the data.

sqd, siga (σ_a) , sigb (σ_b) are, respectively, the square deviation of the function, and the deviations of its coefficients a and b.

cov (σ_{ab}) is the covariance of a and b.

mvs-tc-output.dat

mfilename chr[chr #] mvx-vx a b sqd siga sigb cov pairs#

where:

mfilename is the character string that labels the analysis data, and contains information what files were combined for the analysis (see mvs-tc-driver).

5. Mongo Files

All files that have a suffix .mon are mongo source code files. There are two types of such files: p[][].mon and f[]-[]-[].mon files.

Every mongo file is used to create a hardcopy plot of the data file associated with the mongo file. A plot is obtained by typing:

mongo [mongo-filename]

p[mode][mvr #].mon plots include both the p[mode][mvr #].dat data (square dots) and the tl[mvr #].dat data (broken line). f[flite #]-[temperature]-[mode].mon files produce four plots out of the associated f[]-[]-[].dat data for different combinations of the channel range and choice of mvl-vl or mvu-vu pairs of data (square dots).

6. Fortran Files

Files that end with .f are FORTRAN 77 source code files. There are five such files: tl1.f, tl2.f, dns-code.f, mvs-code.f, and mvs-tc-code.f. The sequence of UNIX commands:

f77 -o execfile filename.f execfile

performs a compilation of the source code and an execution of execfile, the generated object file.

tl1.f & tl2.f:

These programs generate the theoretical DN-MV pairs assuming the following exponential functions:

$$MV = e^{-(255-DN)t/\tau} \tag{1}$$

for tl1.f i.e. mvr# = 1

$$MV = 10 e^{-(255-DN)\iota/\tau}$$
 (2)

for tl2.f, i.e., mvr# = 2

where $t = 4.34 \,\mu\text{s}$, $\tau = 482.55 \,\mu\text{s}$ and $0 \le \text{DN} \le 255$ (From A. Mavretic's lab notebook labeled book 2, #254, July 1974). Note that $e^{t/\tau} = 10^{1/256.0167}$ for these values.

dns-code.f:

This program does a least squares fit by analyzing the p[][].dat data files, and presuming that MV and V are related by the following exponential relation:

$$MV = c_1 e^{-(255-DN) c_2}$$
 (3)

where c_1 and c_2 are constants that are determined by the fitting procedure.

The program produces the file dns-output.dat. The algorithm used is a modification of the general least squares algorithm that makes the round-off errors as small as possible.

mvs-code.f:

This program uses the same algorithm as the previous one. It presumes that MV and V are connected with the following relation:

$$V = a MV + b \tag{4}$$

where a and b are constants that are determined by the fit.

The program analyses the f[]-[]-[].dat data files, dividing each file into four parts using the driver file. Every part is characterized by a unique channel range and mv range (mvr). The analysis, i.e., the least squares fit is carried out independently for each part. The file mvs-output.dat contains the results from the analysis.

The formulae used to calculate the deviations of the obtained coefficients are:

$$\sigma_a = \left(\frac{\sigma^2}{\Delta} \sum_i M V_i^2\right)^{1/2} \tag{5}$$

$$\sigma_b = \left(N \, \sigma^2 \, / \, \Delta \, \right)^{1/2} \tag{6}$$

$$\sigma_{ab} = -\sum_{i} MV_{i} \sigma^{2} / \Delta \tag{7}$$

where

$$\Delta \equiv N \sum_{i} MV_{i}^{2} - \left(\sum_{i} MV_{i}\right)^{2}$$

and

$$\sigma^2 \equiv \frac{N}{N-2} \ sqd \tag{8}$$

with N the number of MV-V pairs.

mvs-tc-code.f:

This program employs the same least squares fit algorithm as the previous two. It presumes the same relation between MV and V, and performs the same analysis as mvs-code.f does, except that it internally combines the f[]-[]-[].dat data files that differ only by temperature. The results of the analysis are contained in the file mvs-tc-out.dat.

7. DN-MV Analysis

The primary goal of this analysis was to find out how much the theoretical DN-MV formulas are off from the true values. The only information available is from the calibration tests performed on the PLS-Prototype. This information was severely limited - only one test, at unknown temperature, per channel in each mode. Also, there is no information on the measurement uncertainties. Hence, the analysis results should be used with some caution. consideration.

The mongo plots of DN-MV data files (DN vs. log MV) show that DN and MV are related through an exponential relation. The DN-log(MV) pairs, as can be seen from the plots, lie on a straight line which, however, has a slightly different slope and y-axis intercept than the theoretical line. This suggested that there might be some non-linearity in the A/D conversion, if one assumes that DN's and MV's were measured at the same time. In addition, the slope and intercept shifts are bigger for mvr1 (0.1 $\leq MV \leq 1.0$) than the corresponding shifts for mvr2. This implies that the multiplication factor in the DN-MV formula for this range is not exactly 10.

The investigation of the plots sugested that the presumed function for the least square fit be:

$$MV = c_1 e^{-(255 - DN) c_2}$$
 (9)

The program actually uses a linear least squares fit algorithm. If we take ln of the both sides of the equation, we obtain:

$$\ln MV = (DN - 255) c_2 + \ln c_1 \tag{10}$$

which can be considered as a linear function y = ax + b setting: x = DN-255; $y = \ln MV$; $a = c_2$; $b = \ln c_1$.

Before the data files were used for the analysis, all DN-MV pairs which were significantly off the imagined line that connects the other points on the mongo plots were deleted. They obviously represent a subjective reading, or even a writing, error.

The analysis results show that the presumed function yields a good approximation, since the square deviation is less than 10^{-6} in most cases. The multiplication factor c_1 ranges from:

```
1.02831 \rightarrow 1.02864 instead of 1 for mvr1 (2.831% \rightarrow 2.864%)
9.91158 \rightarrow 9.92186 instead of 10 for mvr2 (-0.8842% \rightarrow -0.7814%)
```

The range deviations for c_1 in percentages are:

mvr1: ± 0.016% mvr2: ± 0.052%

is surprising that the $c_1(\text{mvr2})/c_1(\text{mvr2})$ ratio is less than 10; it ranges from 9.63880 \rightarrow 9.64560. This implies that PLS circuitry constants responsible for the multiplication factor might be off by ~3.5% from their nominal value(s).

The constant in the exponent, $c_2 = t / \tau$, ranges from :

 $0.888580 \times 10^{-2} \rightarrow 0.889623 \times 10^{-2}$ instead of 0.899388×10^{-2} (1.201% \rightarrow 1.085%).

The range deviation for c_2 is $\pm 0.058\%$.

If we consider t (the period of the fast A/D converter) as constant, then the time constant τ might be off (bigger) 1.085% \rightarrow 1.201% from the nominal value of 482.55 μ s, or, on an average, by \sim 1.15%.

8. MV-V Analysis

The goal of this analysis was to determine the proportionality constants between the monitor low voltage and high voltage (i.e., the actual grid potential). The low voltage is (nominally) proportional to the high voltage applied to the modulator grids (at least in the linear regime of the amplifiers). The theoretical value of this factor is not known, although it can, in principle, be derived from the circuit diagrams.

The analysis uses the results of the power supply test, conducted by Matrix Research and Development for two of the PLS instruments (refer to discussion in section 2). The tests were performed for several temperatures. Although all modes were incorporated in the measurements, the files were highly incomplete and difficult to read (handwritten). As is the case with the DN-MV analysis, there is no information on the measurement uncertainties.

All of the plots of MV-V data files clearly show that MV and V are linearly dependent. Since no information was readily available for the theoretical factor of proportionality, the plots do not include any theoretical graphs. A simple linear function was presumed for the least squares fit:

$$V = a MV + b (11)$$

Similar to the DN-MV analysis, all MV-V points with unusually large deviations from this function were deleted from the files.

Throughout the analysis, every file is divided into four parts (with an exception of mode E1 files which are divided into two parts with respect to mvr). Each part has a unique channel range (chr1 or chr2), and monitor monitor voltage range (mvr1 or mvr2). These parts are processed independently.

The analysis results (file mv-output.dat) are somewhat surprising. First, the square deviation ranges from roughly 10^{-5} to over 350 (considering least squares fits of more than 2 data pairs). This might be evidence of harsh measurement errors during the test or strong non-linear influences in the PLS circuit. The random distribution of the square deviation values shows that the errors or influences are not dependent on factors such as: temperature, mode, voltage or channel range. The deviations obtained for a and b, as well as the covariance of a and b, show a much more stable picture; their median values are, roughly, as follows:

$$\sigma_a \sim 0.1$$
 $\sigma_b \sim 0.1$
 $\sigma_{ab} \sim -10^{-2}$

It is interesting that the values obtained for a and b show an obvious dependence on various factors, although, ideally, they should not. If one looks at the values for the slope a, it can be seen that in 90% of the cases:

```
a(mvl-vl) > a(mvu-vu)
```

There are only eight cases where this relation does not hold true; since these cases appear to be totally random with respect to any factors that might have influenced them (temperature, specific mode, etc.), the observed property may serve as an evidence that some circuit constants change when switching from the lower to the upper channel edge.

The ratio a(chr2)/a(chr1) randomly oscillates around the value of 10, which is the nominal value for the multiplication voltage factor when the instrument switches from the first channel range to the second channel range. The stability of this multiplication factor shows that the circuit constants for the appropriate part of the circuit are close to their nominal values.

This situation, however, changes in considering the dependence of the slope of a on the mode. The values of a for various modes vary roughly as follows:

```
1-mode ..... a = 60.5; 605.1 m-mode ..... a = 60.3; 603.5 e1-mode .... a = 67.2 e2-mode .... a = 68.1; 672.1
```

The slight difference between a(1-mode) and a(m-mode) can be noticed in many cases, especially considering values of a which correspond to a smaller square deviation and larger number of analyzed MV-V pairs. On the average, a(1-mode) is 0.33% larger than a(m-mode). Following the same criterion, one notices that a(e1-mode) and a(e2-mode) differ more drastically from a(1-mode) and a(m-mode). The percentage increase from a(m-mode) turns out to be, roughly:

```
a(e1-mode) ..... 11.45% a(e2-mode) ..... 12.93%
```

This suggests that some circuit constants in both E modes differ from their nominal values.

The last consideration for the slope values is whether or not they are temperature dependent. It is important to note, once again, that the analysis was limited to five different temperatures. The values of a do not show any dependence on temperature; they tend to oscillate randomly as the temperature increases. This observation is consistent with the theoretical expectations.

The values of b, which represent the y-axis intercept or the voltage offset are much more randomly distributed than are the slope values. In fact, b values vary so much that no dependence property can be uniquely established.

The values of b vary from -40 to +40; however, most of them are between -5 to 0. In roughly 90% of cases the values are negative. Theoretically, the values of b should be close to 0. Typical values for b are (roughly):

```
-0.4 ... for chr1 -1.5 ... for chr2
```

9. MV-V Temperature-combined Analysis

Since the slope values did not show any dependence on temperature, all families of files that differed only by temperature were collapsed, and the data from the corresponding parts of these files combined for the least squares fit. The result of this analysis is the file mvs-tc-out.dat. First, it can be noticed that the lower edge of the square deviation range has moved toward larger values (from $\sim 10^{-5}$ to $\sim 10^{-3}$). The square deviations for a and b, and the covariances are, for the most part, in the same range as in the previous analysis.

The relation:

```
a(mvl-vl) > a (mvu-vu)
```

still holds true for 80% of cases (there are three cases when it does not).

The ratio a(chr2)/a(chr1) oscillates around 10 (the theoretical value) as in the MV-V analysis.

This analysis also confirms that there is a definite dependence of a on the mode. Some spot checks suggest the following percentage differences (with respect to a(m-mode)):

```
a(l-mode) .... 0.13%
a(e1-mode) .... 11.75%
a(e2-mode) .... 12.12%
```

(The median value for a(m-mode) is 60.13.)

The values of b are, again, very randomly distributed, so that no firm property or dependence can be established. For example, $b_{ave} = -4.631$ volts. However, if the first four large values of b are not considered (since they range from -20 to -30), the new,

restricted average value of b becomes: $b_{ave\ res} = -1.153$ volts.

This example clearly shows that it is very difficult to derive any major conclusion about b from the analysis results obtained.

10. Conclusions

The analysis results are surprising in that the derived conversion constants deviate by fairly significant amounts from their nominal values. However, it must be kept in mind that the test results which were used for analysis may be very imprecise. Even if we assume that the test result errors are very large, they do not appear to be capable to account for all discrepancies between the theoretical expectations and the results of the analysis. Measurements with the flight spare instrument appear to be the only means of investigating these effects further.

It is very clear that is impossible to create one simple algorithm that for given DN will return V - the actual grid potential. The MV-V slope dependence on the channel range is what was expected. However, the MV-V slope dependence on whether we have the top or the bottom of the channel, and a dependence of the MV-V slope on the mode, precludes a unique algorithm for all cases.

In order to convert a given DN into the V, we need the following auxiliary information:

- 1 the mode
- 2 the decade the modulator is sweeping through (mvr#)
- 3 the channel range (chr#)
- 4 the channel edge the DN corresponds to (mvl-vl or mvu-vu)

Given the stated information (for 2 and 3 we must rely on the "proper sequence" or an "educated guess"), one can pick up the corresponding constants from the files dns-output.dat and mvs-tc-out.dat, and substitute them in the general formula:

$$V = a c_1 e^{-c_2 (255-DN)} + b (12)$$

to obtain the actual grid potential V. The error in the value obtained will be as large as the errors in the test results the DN-MV-V analysis is based on.

For example: Flite# = 2; Mode = M; mvr# = 2; chr# = 1; channel edge = lower (mvl-vl). The values of the constants in the general DN-V formula, are:

$$c_1 = 9.91168$$
 $c_2 = 0.888609 \times 10^{-2}$
 $a = 60.13527$ $b = 0.71937 \times 10^{-1}$

If the value returned from the PLS instrument is DN = 73, then the grid potential is 118.3 volts.

It is important to note that the general DN-V formula only yields magnitudes; the actual potentials in the E1 and E2 modes will be negative.

11. Description of Tables

Tables 1,2, and 3 are, respectively, hardcopies of the files dns-output.dat, mvs-output.dat, and mvs-tc-out.dat.

12. Description of Graphs

The first set of graphs contains hardcopy plots of p[][].mon mongo files. The second set of graphs contains hardcopy plots of f[]-[]-[].mon mongo files (see section 5).

13. Description of Source Code used in the Analysis

Hardcopy listings (with comments) of the files dns-code.f, mvs-code.f, and mvs-tc-code.f are included.

14. Voyager Memorandum #161

Voyager Memorandum #161 is appended.

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dns-output.dat

filename mvr#	mvr#	c1	c2	sqd	#pairs
pl1.dat	mvr1	1.02839		.390305e-07	9
pl2.dat	mvr2	9.91158	888580e-02	.808982e-08	25
pml.dat	mvrl	1.02831	-:888749e-02	.744256e-06	27
pm2.dat	mvr2	9.91168	888609e-02	.161969e-07	112
pell.dat	mvrl	1.02864	889413e-02	.952267e-06	9
pel2.dat	mvr2	9.92186	889096e-02	.110472e-07	S
pe21.dat	mvrl	1.02835	889623e-02	.169905e-07	4
pe22.dat	mvr2	9.91175	888633e-02	.911977e-08	&

filename	chr#	mvx-vx	es i	q	pbs	siga	sigb	cov(a,b) #	pairs
f1-5-1.dat	chrl	mvl-vl	60.51235	615136	.997313e-01	0.608705e-01	0.201473	942402e-02	
f1-5-1.dat	chr1	man-nam	60.02615	100870e-02	.302430e-02	0.791282e-02	.36714	08679-0	o a
f1-5-1.dat	chr2	mvl-vl	604:11932	-5.96604	8.40119	561085	4	03286	o a
f1-5-1.dat	chr2	mvu-vu	600.65253	150051e-01	.186472		32592	17005	0 0
f1-5-m.dat	chrl	mvl-vl	60.34817	341069	.473071		0.297130) ~	ہ د
f1-5-m.dat	chr1	mvu-vu	60.08419	824708e-01	.763699e-04	•	37931		9 6
f1-5-m.dat	chr2	mvl-vl	602.49585	.08361			1.33931	ה ס ע	
f1-5-m.dat	chr2	コンコーショ	600.31244	1.04457	.188948e-01	0.108204e-01		6-03	7 1
f1-5-e1.dat	chr1	mvl-vl	67.21983	-1.27390	.679980e-01	.130648	137156	54335e-01	7.
f1-5-e1.dat	chr1	mvu-vu	67.11500	-1.45989	.311056e-01				91
f1-5-e2.dat	chr1	mvl-vl	67.87886	-1.98333	.302277	123319	.364760	32262e-02 32262e-01	2 -
f1-5-e2.dat	chrl	mvu-vu	67.47765	-1.71838	.929421e-02	•	0.667698e-01	8237036-03	
f1-5-e2.dat	chr2	mvl-vl	678.63385	-26.3247	2.47177	341567)	44043	۰ م
f1-5-e2.dat	chr2	mvu-vu	675.54791	-26.4225	2.26864		1.14571	-,235929	o «
f1-10-1.dat	chr1	mvl-vl	60.45045	426117	.316743e-01	0.597866e-01	0.230206	- 872973e-02	, r
f1-10-1.dat	chr1	mvu-vu	72.17496	-8.81379	4.87331	56180	~~)) () (T
f1-10-1.dat	chr2	mvl-vl	603.90668	-7.29915	.617473	0.290085	5495	38740	י אי
f1-10-1.dat	chr2	mvu-vu	600.80804	0.303848e-01	.282393e-02	0.145803e-01	10480	131706e-02	, m
fl-10-m.dat	chr1	mvl-vl	59.32479	0.597509e-01	.635764e-03	0.556788e-01		138911e-02	, ru
f1-10-m.dat	chr1	mvu-vu	60.11923	648625e-01	.108634e-04	0.711466e-02	0.397385e-02	48202e	· IO
f1-10-m.dat	chr2	mvl-vl	597.16608	45.2825	. 594443	0.191781	1.47048	240137	m
f1-10-m.dat	chr2	mvu-vu	598.60986	18.8517	.265741	0.124042	0.988455	104615	സ
f1-10-e1.dat	chr1	mvl-vl	67.14627	985689	.103264	0.239544	27814	543871e-01	9
f1-10-e1.dat	chr1	四~ ロ へ 四	67.00823	-1.18625	.526322e-01	0.158861	0.206007	271838e-01	9
f1-10-e2.dat	chr1	mvl-vl	66.29117	783868	.566844e-01	0.898739e-01	0.309146	177230e-01	m
f1-10-e2.dat	chr1	man-nam	66.24818	879849	.676344e-02	0.231628e-01	0.110463	170817e-02	m
fl-10-e2.dat	chr2	mvl-vl	679.05194	-23.9143	1.63895	0.531040	2.53468	-1.16171	m
f1-10-e2.dat	chr2	mvu-vu	674.69830	-24.5234	1.28637	0.349951	.2483	679375	က
fl-r-l.dat	chr1	mvl-vl	60.55255	827384	.187547	0.837044e-01	0.276299	177728e-01	8
f1-r-1.dat	chr1	mvu-vu	60.03791	179914	4	•	0.134355e-01		80
fl-r-l.dat	chr2	mvl-vl	605.07617	-9.88383	8.46190	0.564280	2.19736	-1.04325	8
fl-r-l.dat	chr2	mvu-vu	600.67584	-1.54748	.312340	ω.	0.421933	285218e-01	8
fl-r-m.dat	chr1	mvl-vl	60.30745		.691204e-01	.347300e-0	0.882699e-01	156537e-02	14
fl-r-m.dat	chr1	man-na	60.08812	311307e-01	.587022e-04	0.972897e-03	CA	130124e-05	14
fl-r-m.dat	chr2	mvl-vl	603.22913	-7.25629	10.6580	•	1.32739	277331	14
fl-r-m.dat	chr2	man-nam	600.50580	0.712475	.156099	•	0.160388	388917e-02	14
fl-r-el.dat	chr1	mvl-vl	67.27860	-1.34343	.614586e-01	•	0.130295	139753e-01	16
fl-r-el.dat	chr1	mvu-vu	67.02419	-1.53669	.315467e-01	0.827581e-01	0.974193e-01	704037e-02	16
fl-r-e2.dat	chrl	mvl-vl	68.02900	.6514		0.110855	0.327331	279894e-01	8
fl-r-e2.dat	chr1	mvu-vu	67.37809	-1.91325	.194067e-01	0.224682e-01	0.935669e-01	166936e-02	88
fl-r-e2.dat	chr2	mvl-vl	680.25678	-24.7925	.949734	0.212501	0.739772	132532	80
fl-r-e2.dat	chr2	mvu-vu		. 793	139.077	1.90430	8.97744	-14.4294	80
-30-1	chr1	mvl-vl	7	0	4025e-0	.596379e	29132	9299	æ
I1-30-1.dat	chrl	四~口~四	60.04224	429275e-01	.105712e-03	0.257825e-02	0.137505e-01	235406e-04	က

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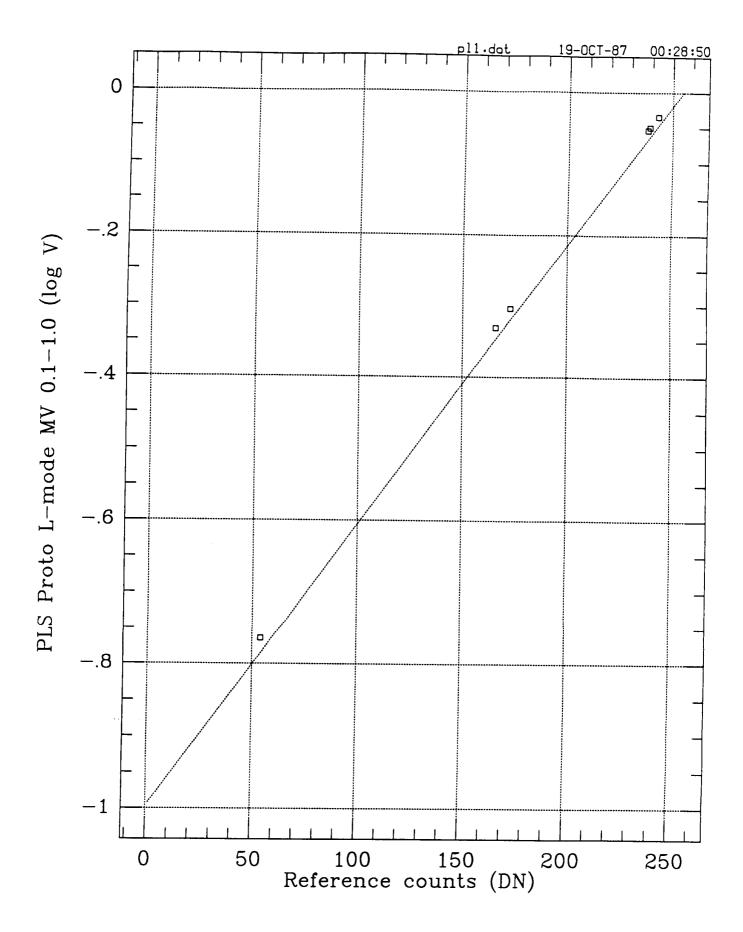
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567367 -175.552 549909e-03 564131e-04 149311e-01	558214e-01 233684e-01 567428e-01 323376e-02 917747e-01	205067e-01 154625e-04 861557 345730e-01 236343e-02	912654e- 368610e- 161221e- 78573e- 179932e- 467641e- 8.4482	13.0675 13.0675 148761 13.1373 1362899 1362899 1362899	344961e-02 166099e-01 780712e-02 268985e-01 168543e-02 272830 -1.11451 219066e-02 676795e-05 -Inf -Inf 190192e-02 190192e-02
1.8735 38.327 .18690 .61445 .36595	0.281414 0.190932 0.552319 0.152103 0.711206	0.296572 0.952460e-02 1.99546 0.464641 0.108467 0.236544e-02	0.786015 0.161213 0.139741 0.102907 0.262077 0.156757	12.9290 8.73213 0.800396e-01 0.712142e-02 0.780893 0.108788 0.425381e-01 0.360352e-02 0.497178	0.151269 0.141911 0.102438 0.320576 0.938107e-01 1.06044 2.48825 0.115361 0.736847e-02 Inf Inf 0.335781e-01
0.351400 5.31187 0.352405e-01 0.107766e-01 0.477435e-01	0.243170 0.147369 0.161272 0.318398e-01 0.149537	0.900174e-01 0.205234e-02 0.513211 0.884640e-01 0.427041e-01 0.890818e-03	0.160787 0.317138e-01 0.134095 0.874581e-01 0.891462e-01 0.375483e-01 3.59806	3.39808 1.80264 .2423176 .1536946 .200297 .2074676 .1664896 .1350126	0.29/158e-01 0.135980 0.873001e-01 0.108755 0.226216e-01 0.305059 0.530712 0.299889e-01 0.138394e-02 Inf Inf 0.656626e-01
.903369 376.736 .211677e-03 .207063e-04 .361189e-01	.105990 .452411e-01 .181260 .128202e-01 .129155	.216349 .203734e-03 6.98169 .378934 .104426	3.84319 .162244 .710135e-01 .352477e-01 .167670 .543690e-01	118.502 .158251e-01 .113892e-03 1.07762 .207434e-01 .160125e-01 .113653e-03 1.53489	.142007 .730523e-01 .349447e-01 .249580 .194963e-01 1.94795 10.6877 .797190e-02 .303788e-04 .155082e-07 .288050e-07 .288050e-07
-7.22915 -5.48300 0.111777 617451e-01 -6.80254	931211 -1.24480 -1.07653 -1.87342 -22.8291	693189 120726 -10.3675 0.102392 378115	-7.98325 1.11681 -1.35274 -1.64349 -1.25709 -2.43097	-36.9362 0.155520 0.327712 0.769367 1.64362 0.194878 0.337415 1.04488	1.818/9 -1.66764 -1.83544 -2.17327 -2.36739 -27.1815 -30.1168 0.129080 0.353142 -1.88010 2.04455 0.269767
69. 1.00. 1.00. 1.00. 1.00.	67.19112 66.98763 68.03098 67.39749 680.48627 673.84424	5784 0204 8693 1124 3011 0839		674.56934 674.56934 60.17648 59.97764 600.51239 60.12848 59.99821 601.54022	2315 2315 2315 2315 2016 2016 2016 2016 2016 2016 2016 2016
mvl-vl mvu-vu mvl-vl mvu-vu mvl-vl	mv1-v1 mv1-v1 mv1-v1 mv1-v1 mv1-v1	mvl-vl mvu-vu mvl-vl mvu-vu mvl-vl mvl-vl	mvl-vl mvu-vu mvl-vl mvl-vl mvl-vl mvu-vu	mvu-vu mvl-vl mvu-vu mvl-vl mvu-vu mvl-vl mvl-vl mvl-vl	mv1-v1
chr2 chr2 chr1 chr1 chr2	chri chri chri chri chri	chrl chrl chr2 chr2 chr1	chr2 chr2 chr1 chr1 chr1	chri chri chri chri chri	chri chri chri chri chri chri chri chri
11111	f1-30-e1.dat f1-30-e1.dat f1-30-e2.dat f1-30-e2.dat f1-30-e2.dat		fl-40-m.dat fl-40-m.dat fl-40-el.dat fl-40-el.dat fl-40-e2.dat fl-40-e2.dat	-400 -5-1.0 -5-1.0 -5-1.0 -5-m.0 -5-m.0	f2-5-e1.dat f2-5-e1.dat f2-5-e2.dat f2-5-e2.dat f2-5-e2.dat f2-10-1.dat f2-10-1.dat f2-10-1.dat f2-10-1.dat f2-10-1.dat f2-10-1.dat f2-10-1.dat f2-10-1.dat

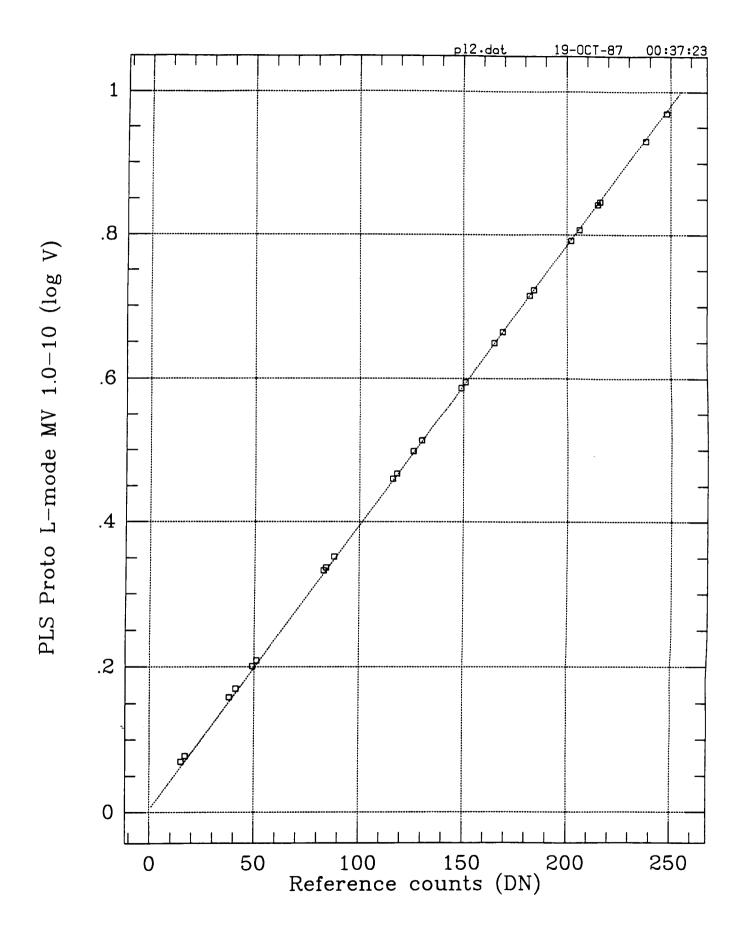
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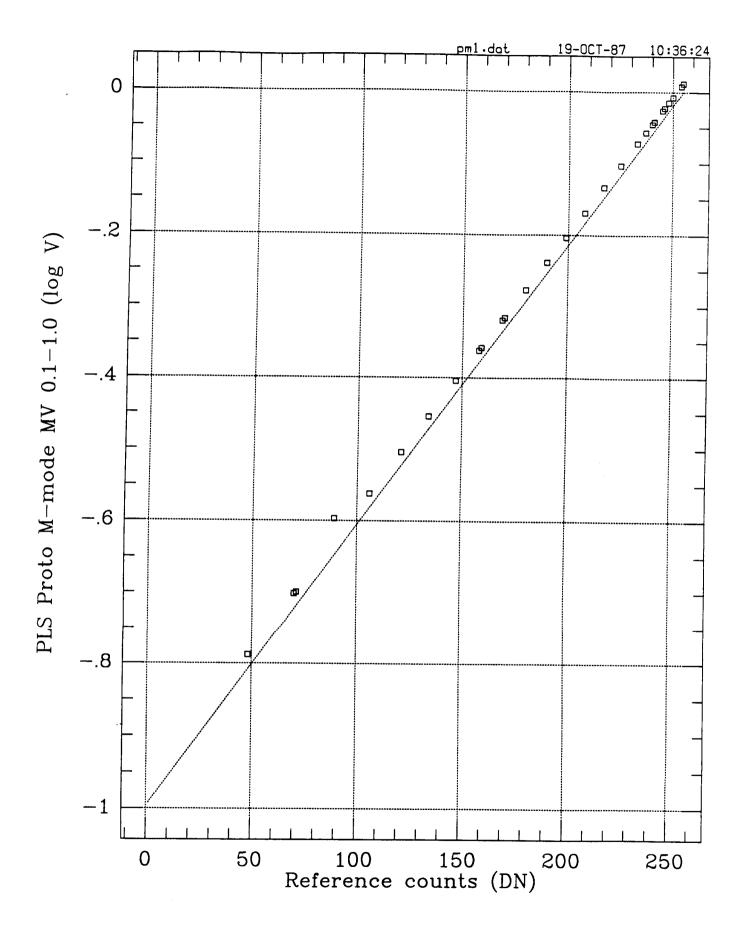
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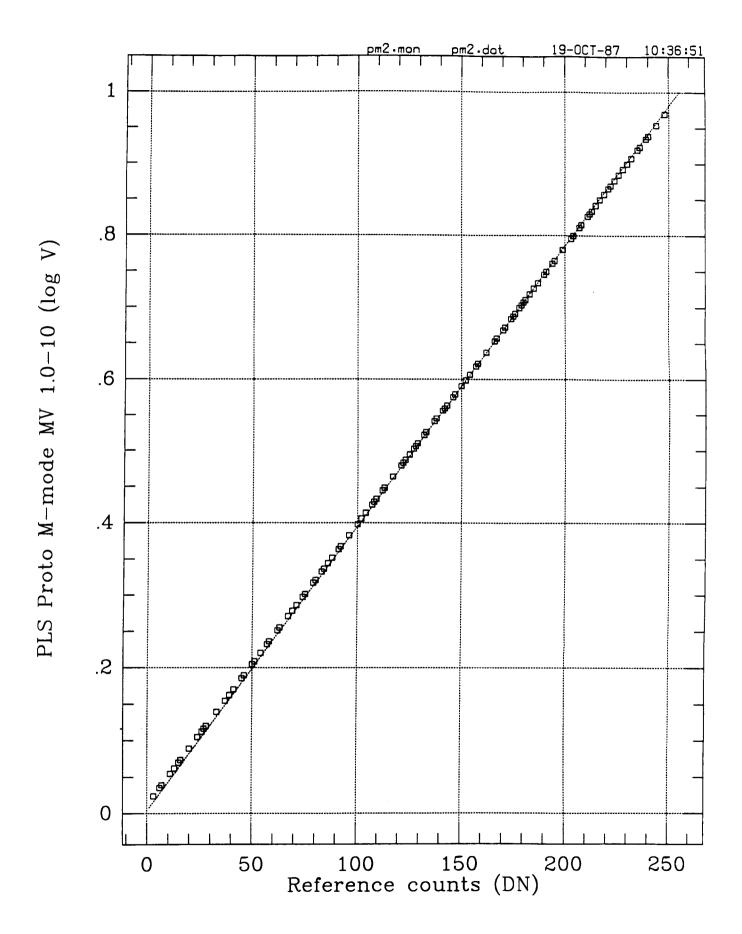
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601.76184 -1.26277 600.48962 2.33135 67.05306 -1.38256 66.92881 -1.67638 67.89469 -1.49594	1978 -24. 9674 -21. 3248 0.56	-1.40088 1.19110 192660e 0.171016 -1.53841	44.44.4	27 20 20 20 30 30 31 30 31	602.09229 -1.60779 600.43127 2.79594 67.22803 -1.45360 66.98215 -1.66388 67.97550 -1.77854 67.39137 -2.29253 681.06494 -24.4491
chr2 mvl-vl 6 chr2 mvu-vu 6 chr1 mvl-vl chr1 mvu-vu chr1 mvl-vl	mv1-v1 mv1-v1 mv1-v1 mv1-v1	chr2 mvl-vl 6(chr2 mvu-vu 6(chr1 mvl-vl (chr1 mvu-vu (chr2 mvl-vl 6(chr2 mvl-vl 6(mv1-v1 mv1-v1 mv1-v1 mv1-v1 mv1-v1	mvu-vu mvl-vl mvl-vl mvl-vl mvu-vu mvl-vl	chr2 mvl-vl 60 chr2 mvu-vu 60 chr1 mvl-vl 6 chr1 mvu-vu 6 chr1 mvl-vl 6 chr1 mvl-vl 6 chr1 mvl-vl 6 chr2 mvl-vl 6
f2-10-m.dat f2-10-m.dat f2-10-el.dat f2-10-el.dat f2-10-e2.dat f2-10-e2.dat		f2-r-1.dat f2-r-1.dat f2-r-m.dat f2-r-m.dat f2-r-m.dat f2-r-m.dat	f2-r-e1.dat f2-r-e1.dat f2-r-e2.dat f2-r-e2.dat f2-r-e2.dat	12-r-e2.dat f2-40-1.dat f2-40-1.dat f2-40-1.dat f2-40-1.dat f2-40-m.dat	12-40-m.dat f2-40-m.dat f2-40-el.dat f2-40-el.dat f2-40-e2.dat f2-40-e2.dat f2-40-e2.dat

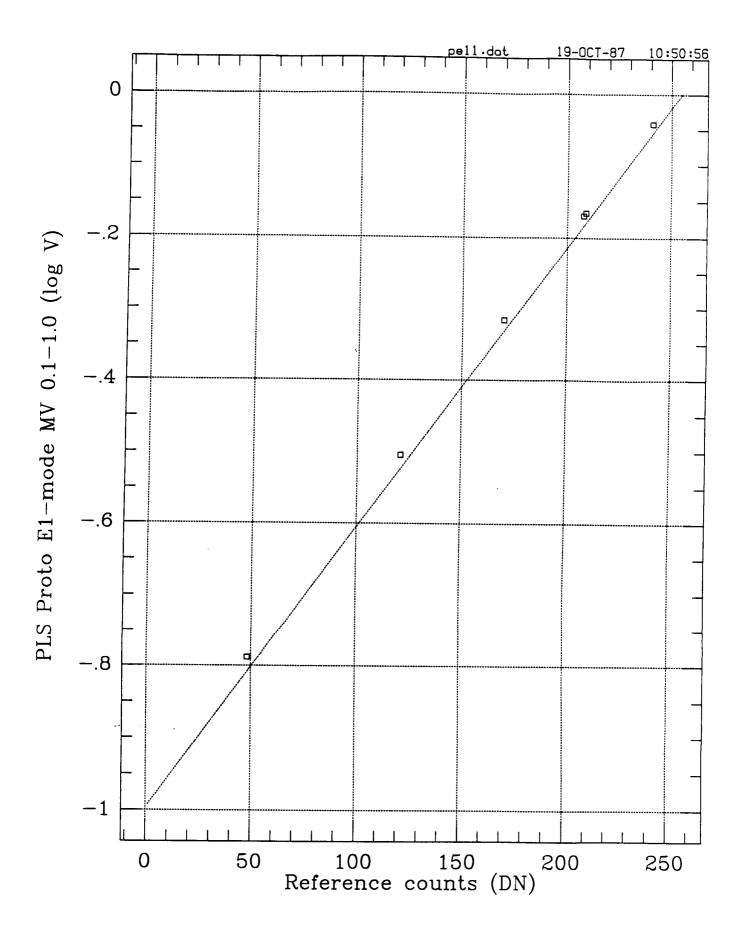
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:1-1.dat	chrl	mvl-vl	60.52104	610043	.164336	0.331425e-01	0.113269	157042e-01	30
1-1.dat	chrl	man-na	61.98012	-3.78736	301.191	1.05781	5.06098	126347e-01	30
:1-1.dat	chr2	mvl-vl	604.74603	-8.13411	10.7494	0.269372	1.13736	223076e-01	9 6
:1-1.dat	chr2	ma-nam	600.16797	973543e-01	58.6173	0.466305	2.65526	165305e-01	9 6
fl-m.dat	chr1	mvl-vl	60.31631	353374	.170454	0.296164e-01	0.714492e-01	603742e-02	47
[1-m.dat	chrl	ma-nam	60.08471	510478e-01	.505415e-03	0.154998e-02	0.391030e-02	591564e-02	47
fl-m.dat	chr2	mvl-vl	602.76862	-4.90454	52.3157	0.293152	1.52384	597133e-02	50
fl-m.dat	chr2	man-nam	600.36346	1.54410	5.37263	0.902943e-01	0.487818	572787e-02	20
<pre>£1-e1.dat</pre>	chrl	mvl-vl	67.24926	-1.24871	.875493e-01	0.690395e-01	0.738429e-01	478687e-01	09
fl-el.dat	chrl	man-nam	67.03070	-1.48414	.661700e-01	0.556784e-01	0.669305e-01	470001e-01	09
fl-e2.dat	chr1	mvl-vl	67.72772	-1.22783	3.10232	0.162477	0.496514	176905e-01	29
f1-e2.dat	chr1	mvu-vu	67.19755	-1.67142	2.24984	0.102853	0.441530	142202e-01	29
f1-e2.dat	chr2	mvl-vl	678.07275	-21.2894	124.611	1.03011	3.92660	252968e-01	29
fl-e2.dat	chr2	mvu-vu	674.68091	-30.3143	106.165	0.707489	3.63723	189183e-01	29
£2-1.dat	chr1	mvl-vl	60.21009	0.735942e-01	.239714e-01	0.138893e-01	0.467219e-01	187701e-01	27
£2-1.dat	chrl	ma-nam	59.95467	0.264793	.223082e-01	0.100075e-01	0.471735e-01	151654e-01	27
£2-1.dat	chr2	mvl-vl	602.88281	773320	2.68548	0.149835	0.601851	257683e-01	26
f2-1.dat	chr2	ma-nam	600.25501	1.39881	2.25701	0.102482	0.553832	193295e-01	26
f2-m.dat	chrl	mvl-vl	60.13527	0.719373e - 01	.265907e-01	0.116207e-01	0.281091e-01	590580e-02	47
f2-m.dat	chrl	ma-nam	59.98359	0.245631	.822439e-02	0.621848e-02	0.157195e-01	580673e-02	47
f2-m.dat	chr2	mvl-vl	601.85620	658335	2.10953	0.628142e-01	0.313642	646934e-02	47
f2-m.dat	chr2	ma-nam	600.52618	2.08670	2.36698	0.640338e-01	0.332164	622361e-02	47
f2-e1.dat	chr1	mvl-vl	67.20400	-1.48642	.900689e-01	0.776666e-01	0.805384e-01	570088e-01	53
f2-e1.dat	chr1	ma-nam	67.27348	-2.35832	7.48046	0.656644	0.766262	560609e-01	53
f2-e2.dat	chrl	mvl-vl	67.94134	-1.87212	.298369	0.553911e-01	0.166032	214916e-01	27
f2-e2.dat	chrl	ma-nam	67.42473	-2.28871	.418198e-01	0.154045e-01	0.650145e-01	172369e-01	27
f2-e2.dat	chr2	mvl-vl	681.07147	-25.5305	2.97343	0.178696	0.639013	295865e-01	26
f2-e2.dat	chr2	man-na	674.81555	-26.0345	31.2612	0.429203	2.07553	219703e-01	26

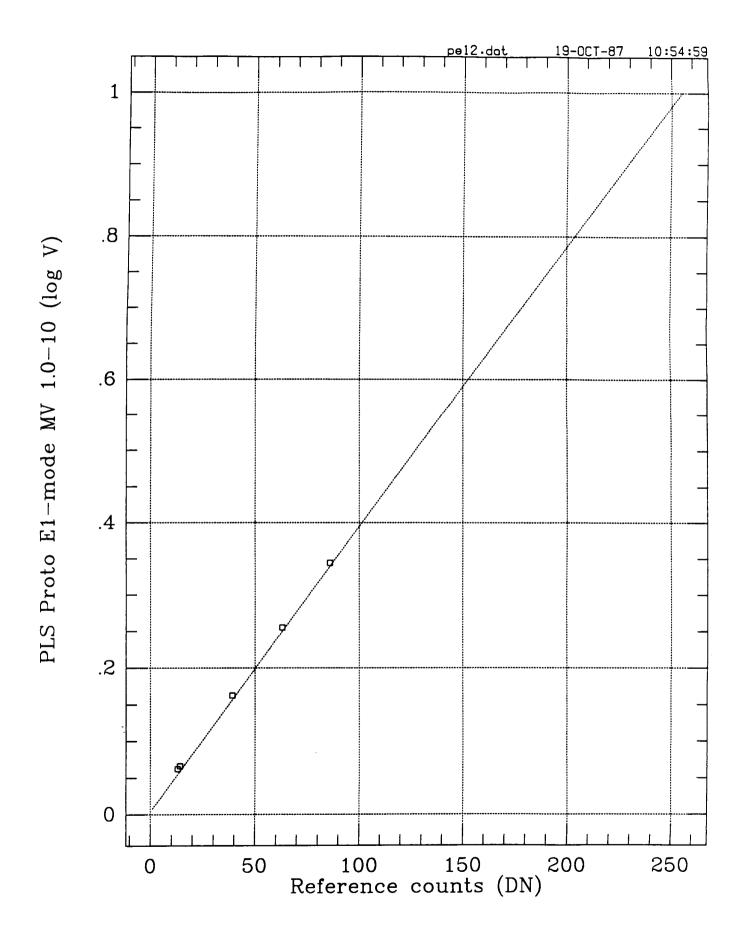


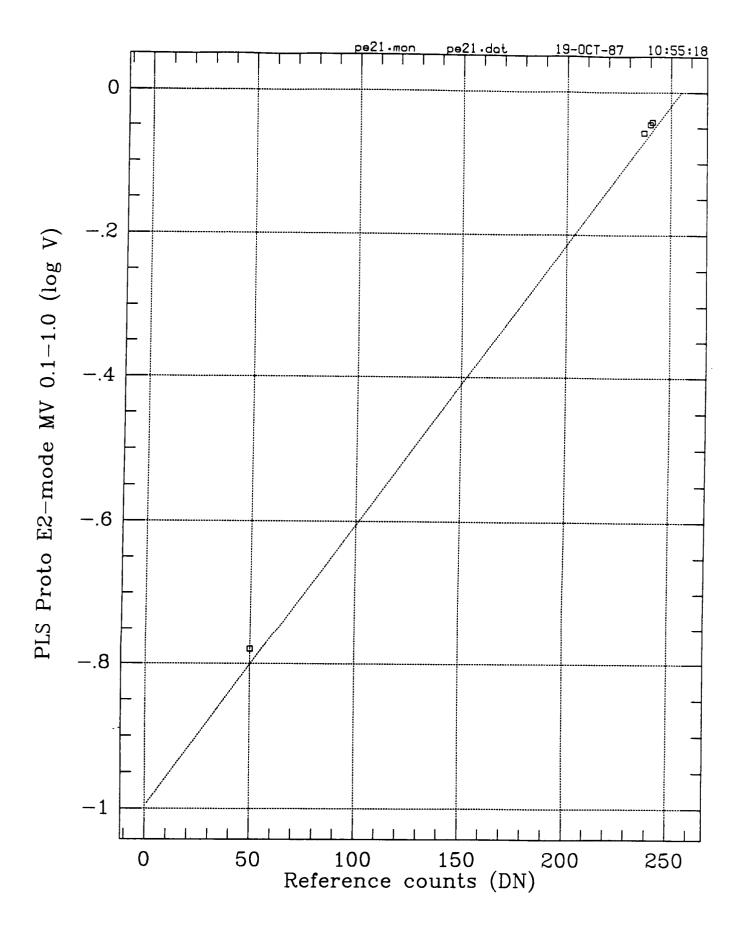


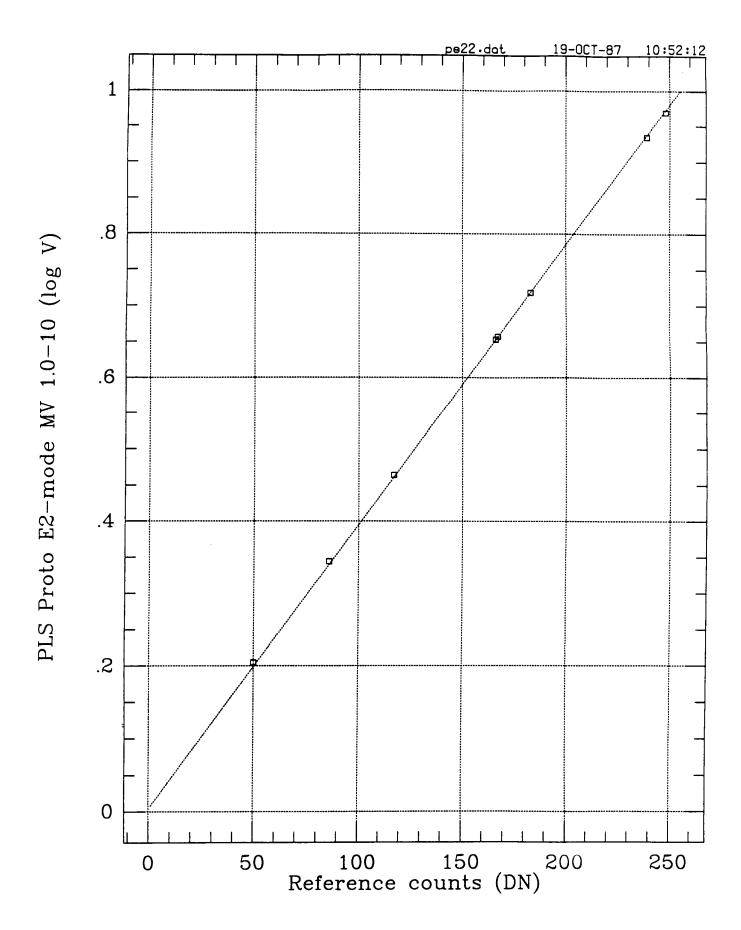


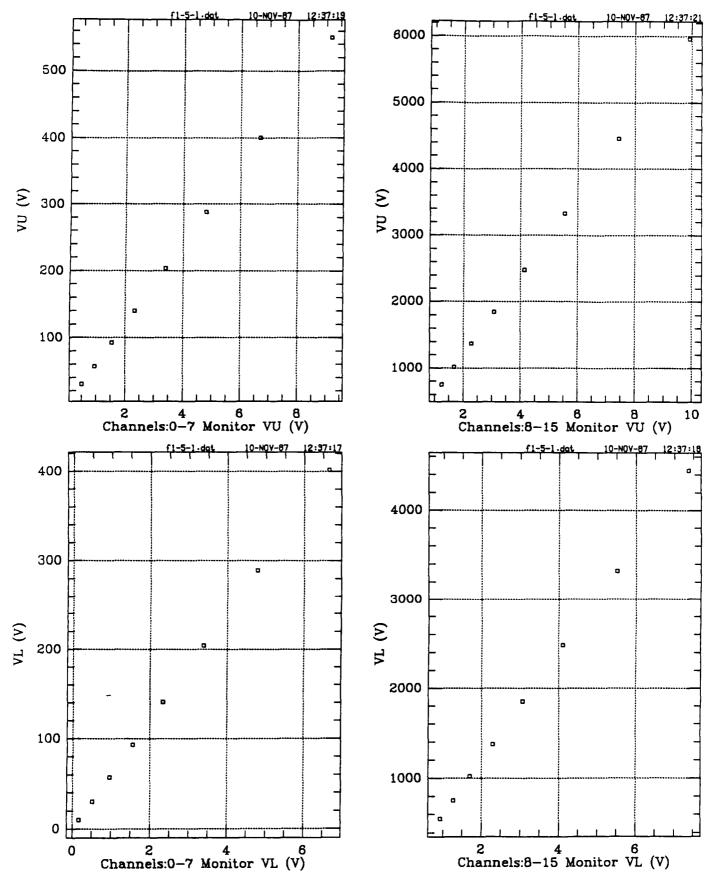




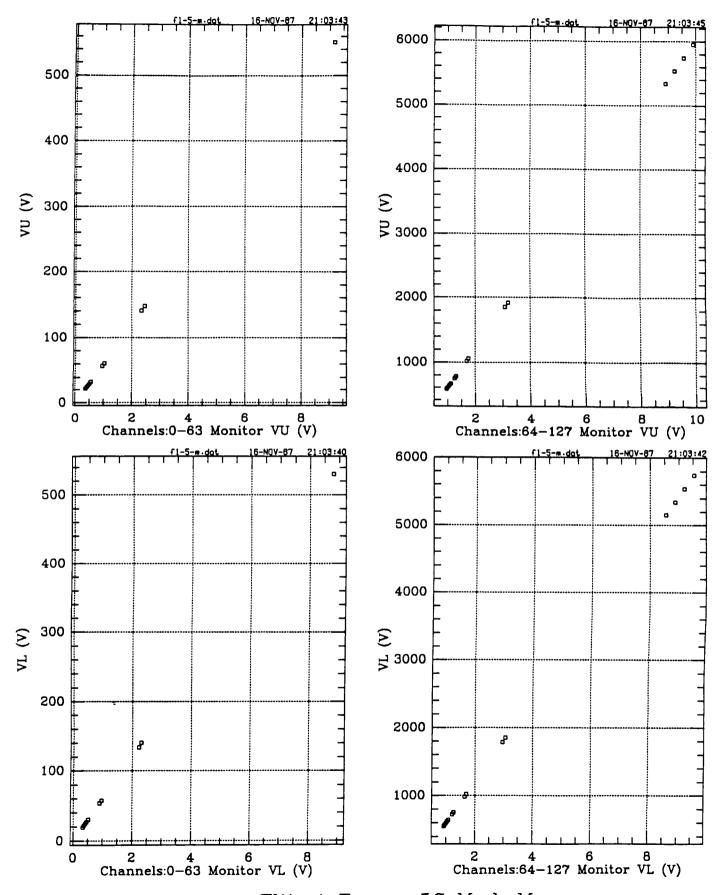




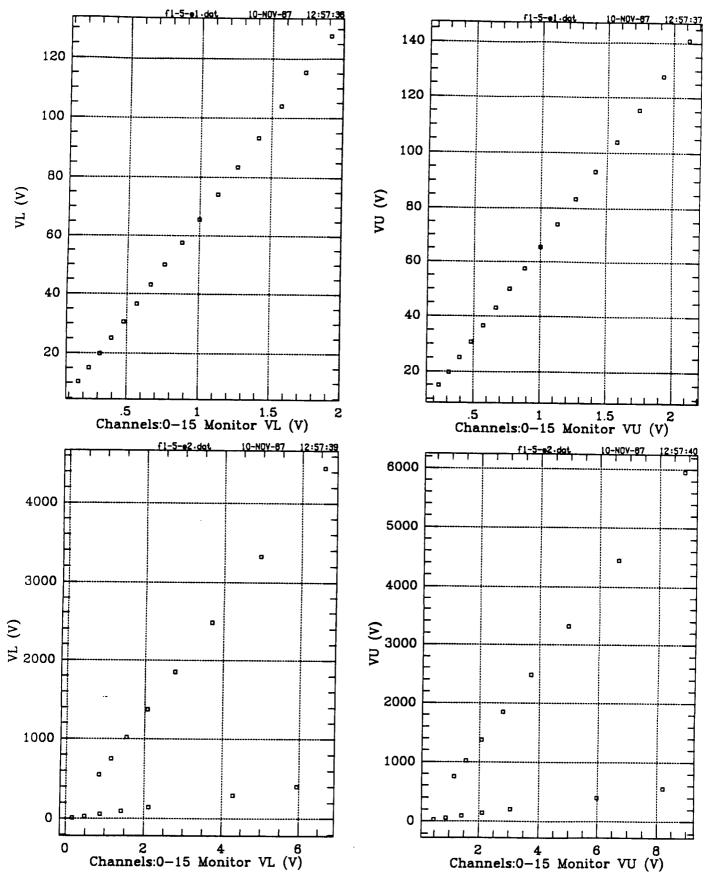




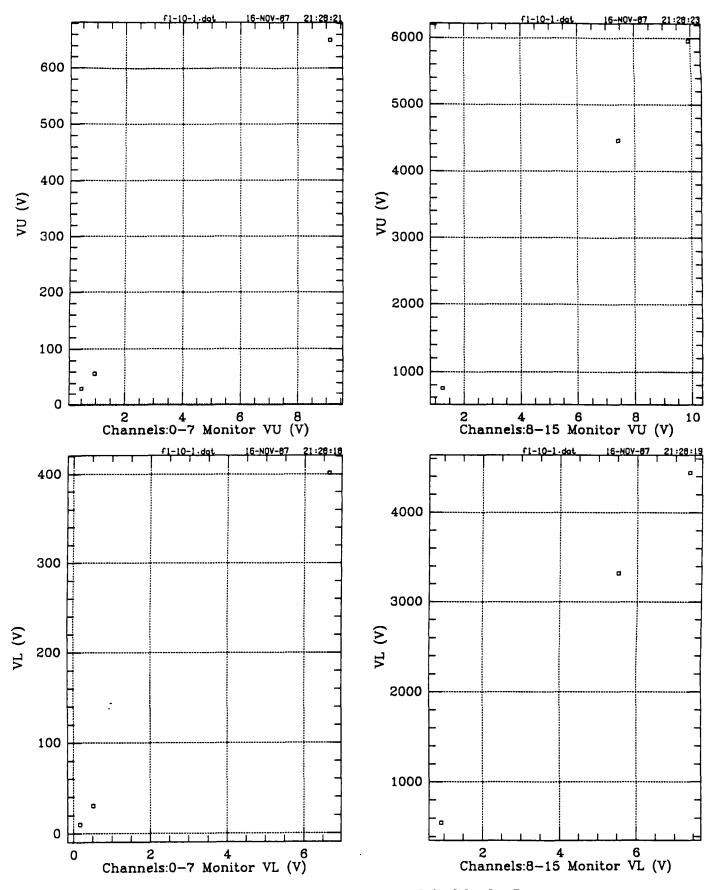
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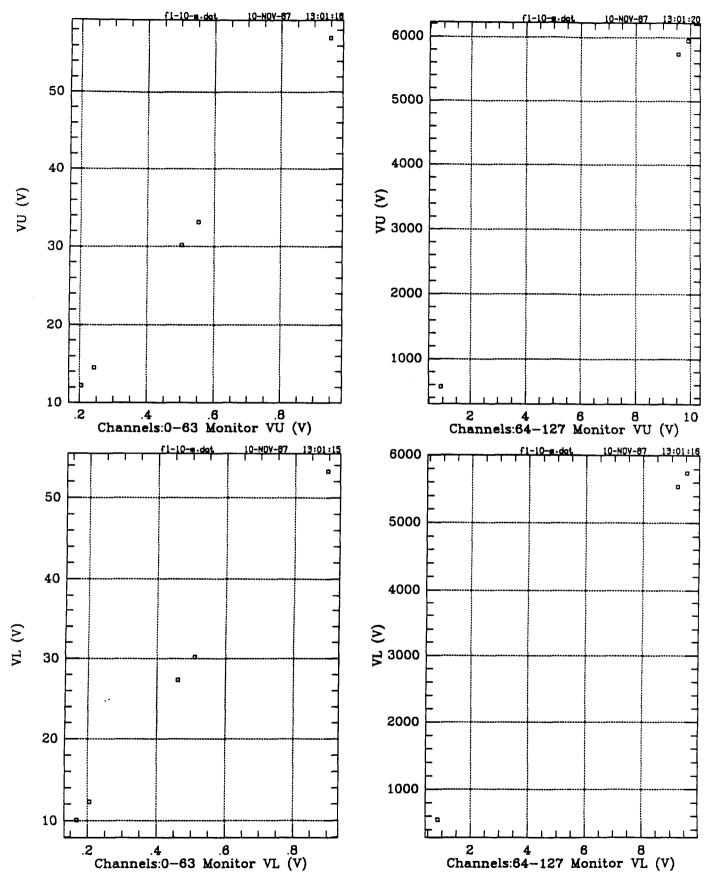
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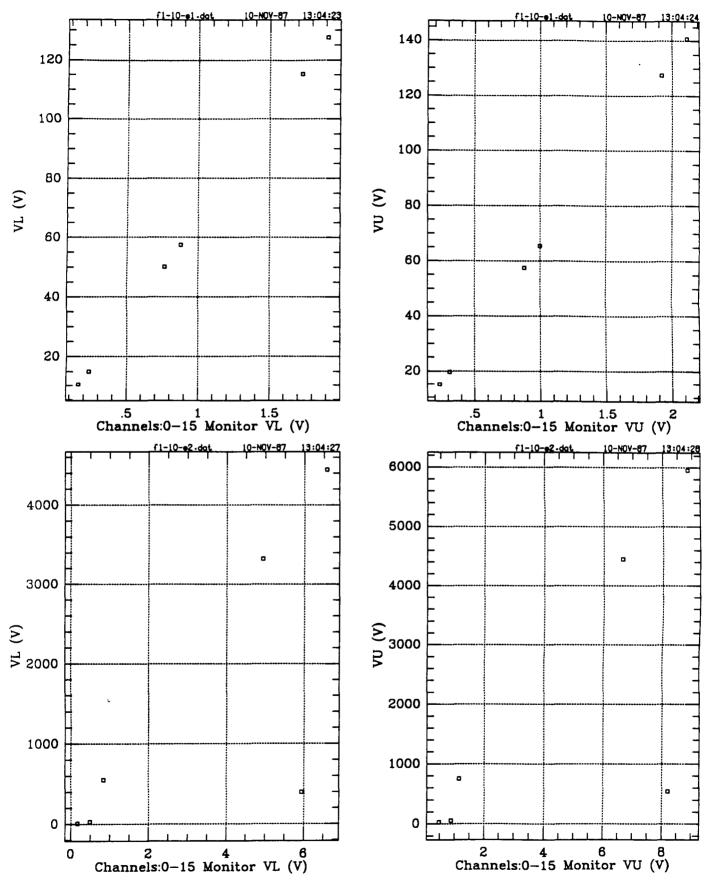
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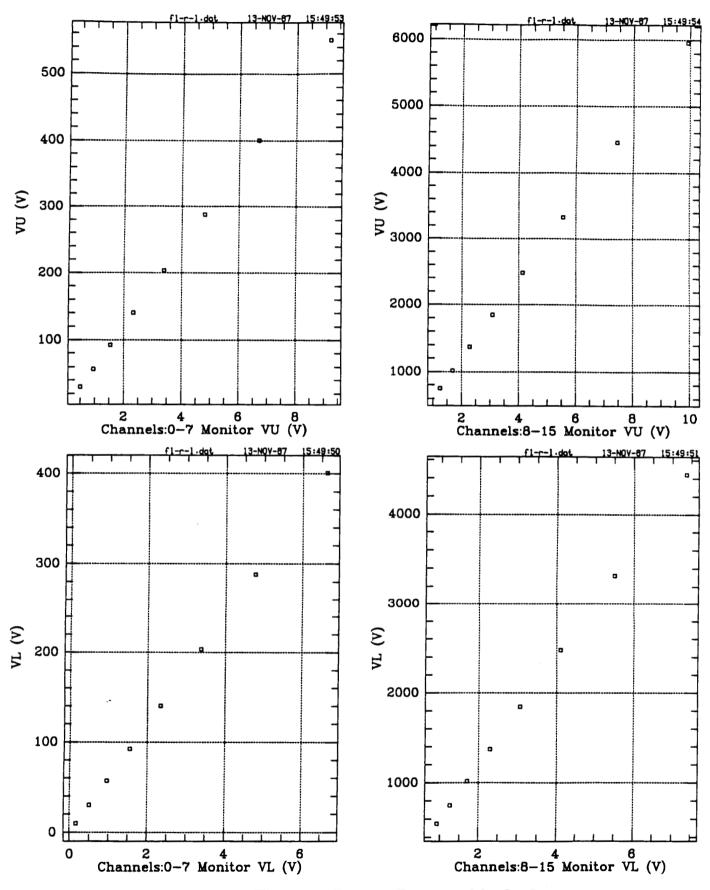
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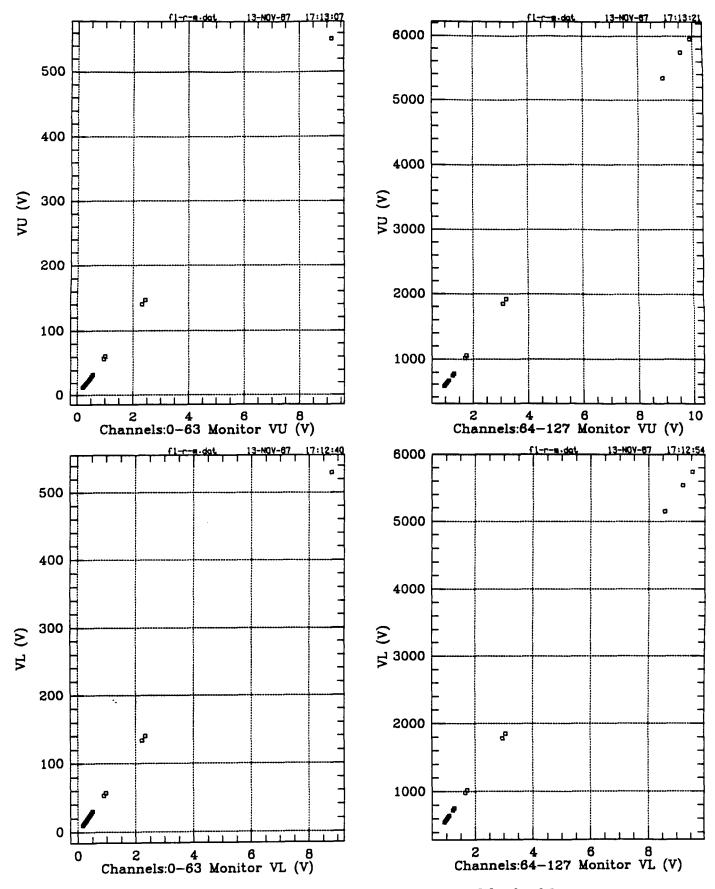
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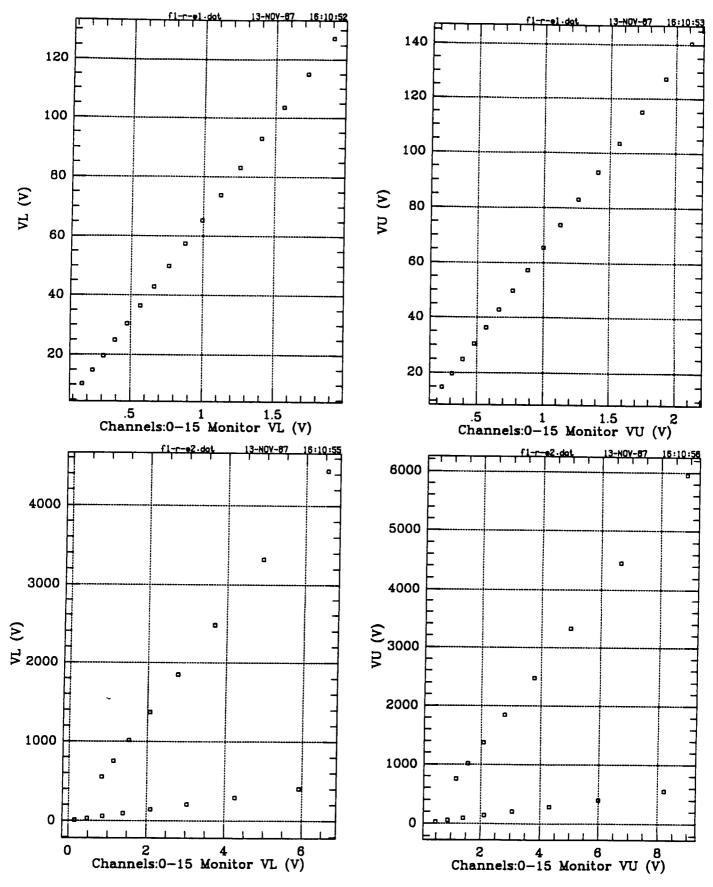
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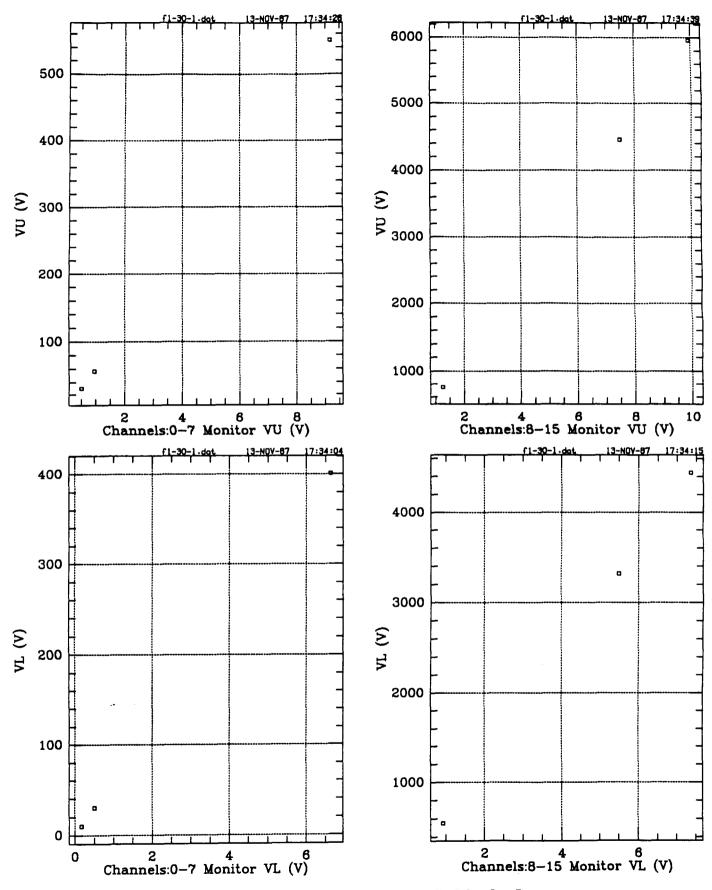
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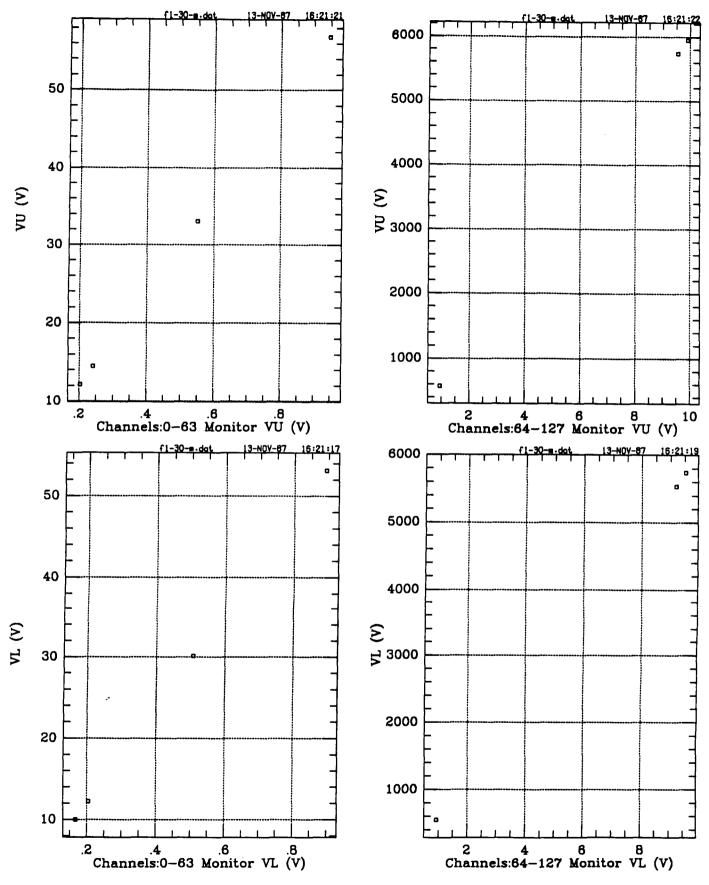
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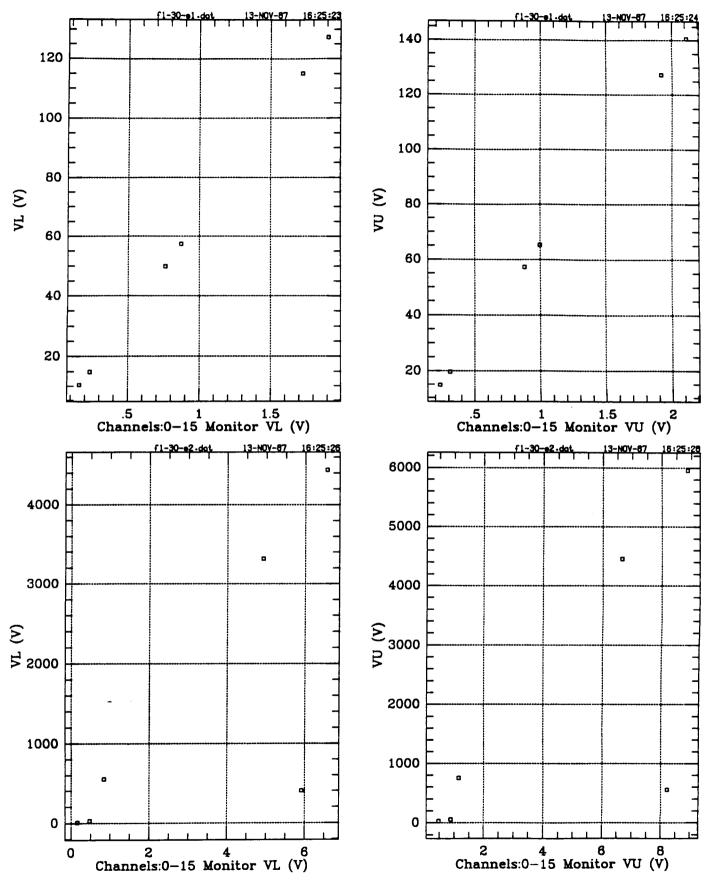
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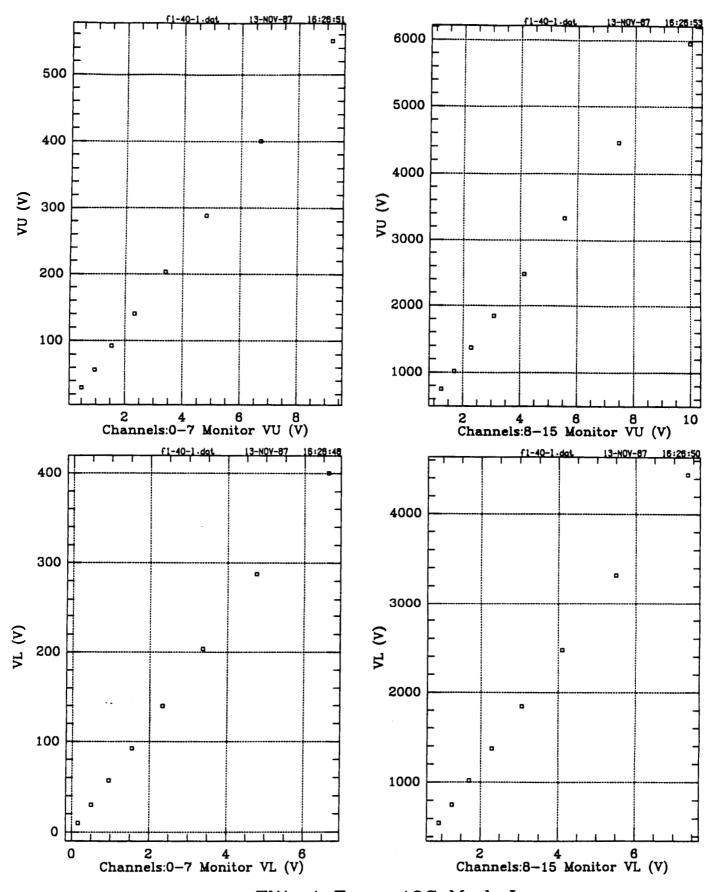
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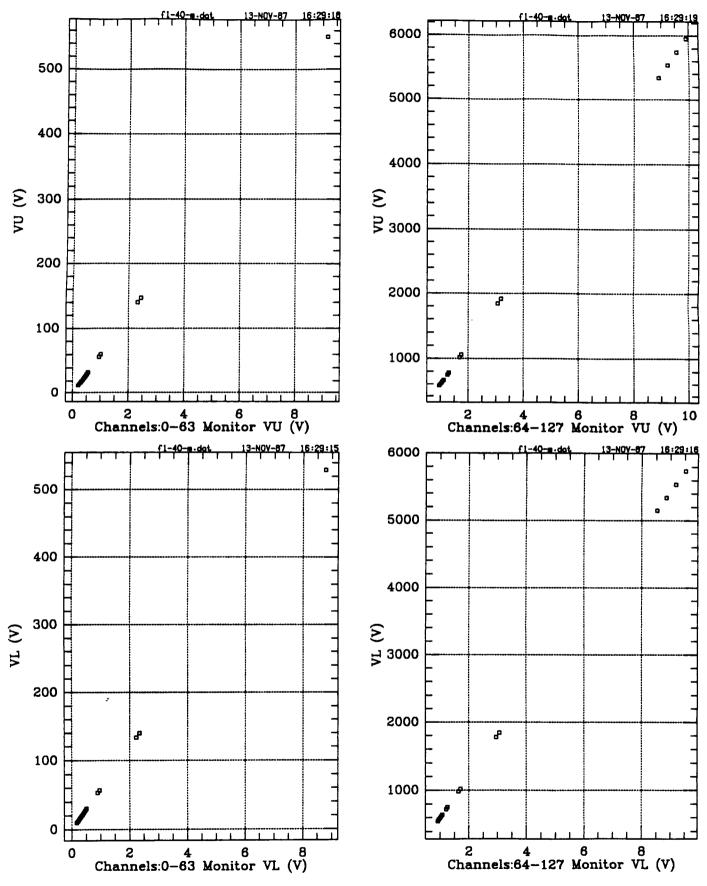
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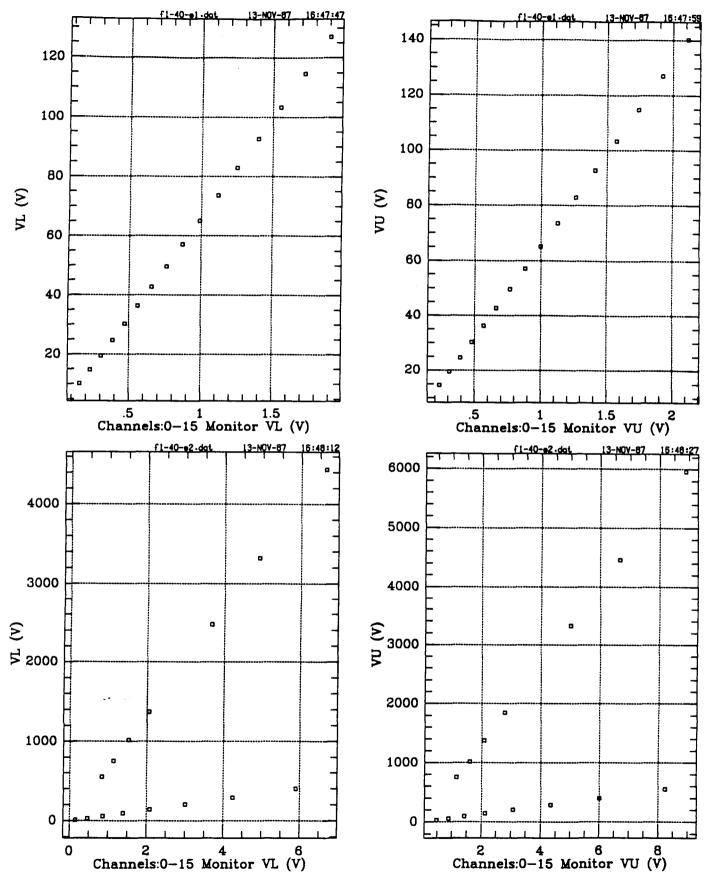
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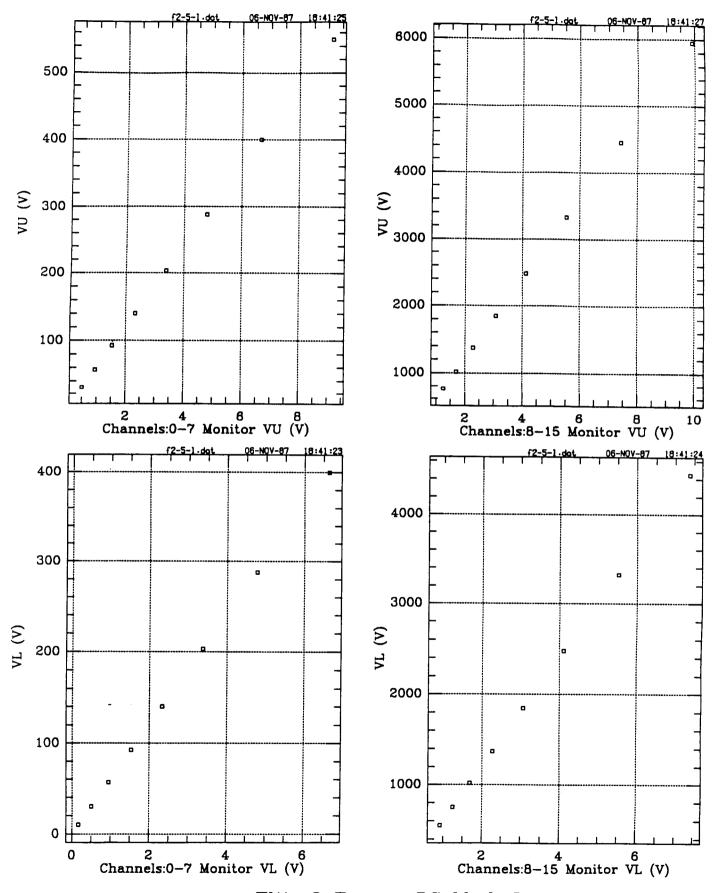
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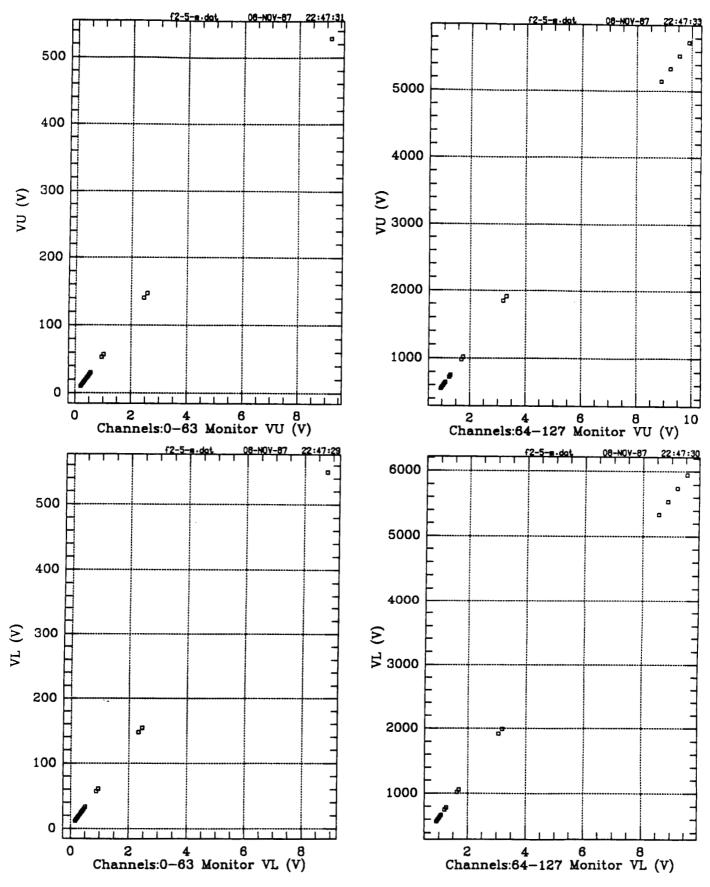
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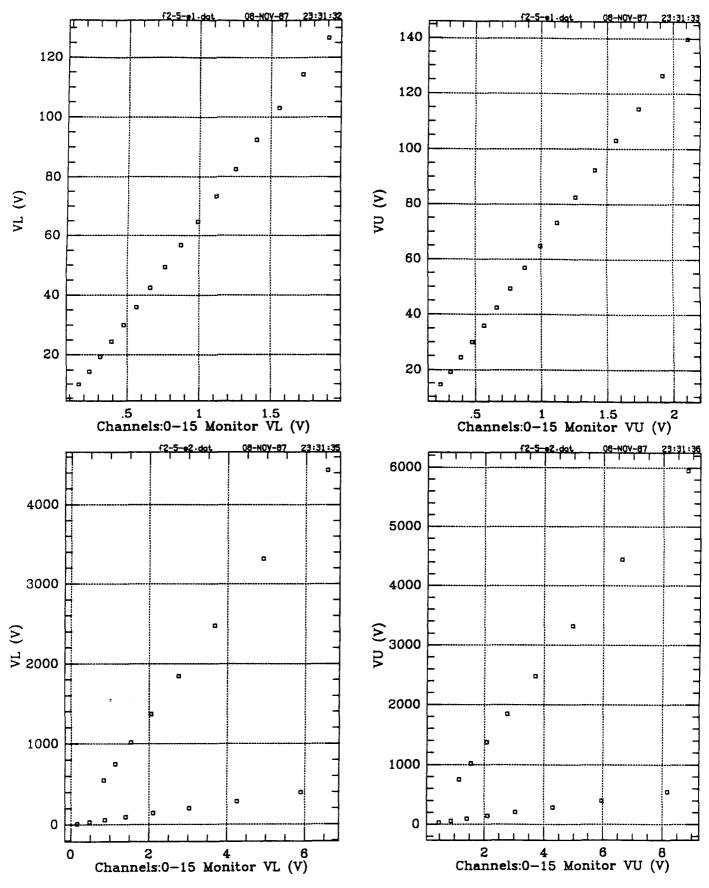
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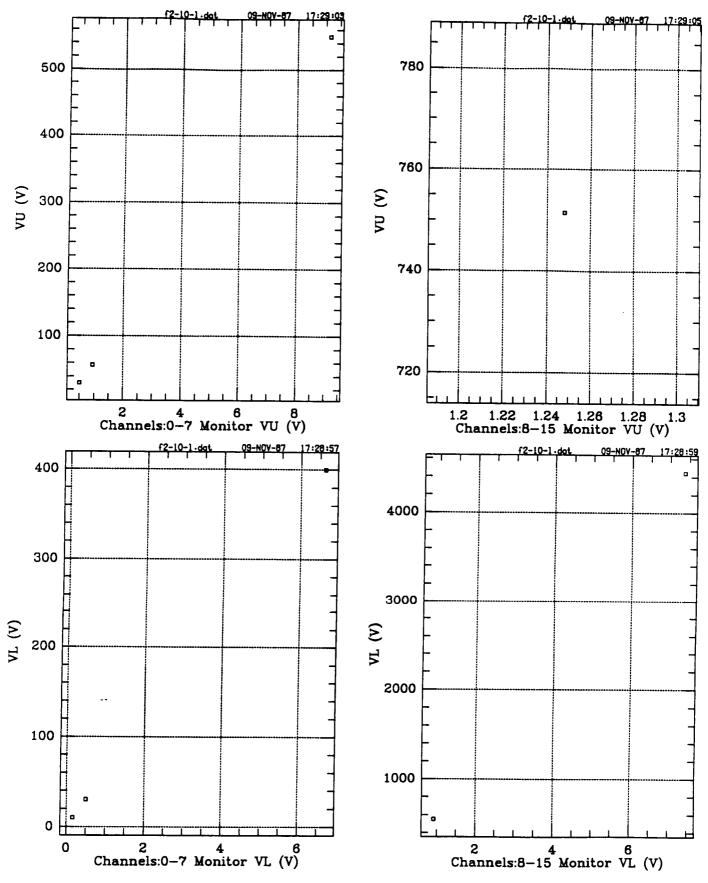
Flite:2 Temp:-5C Mode:L



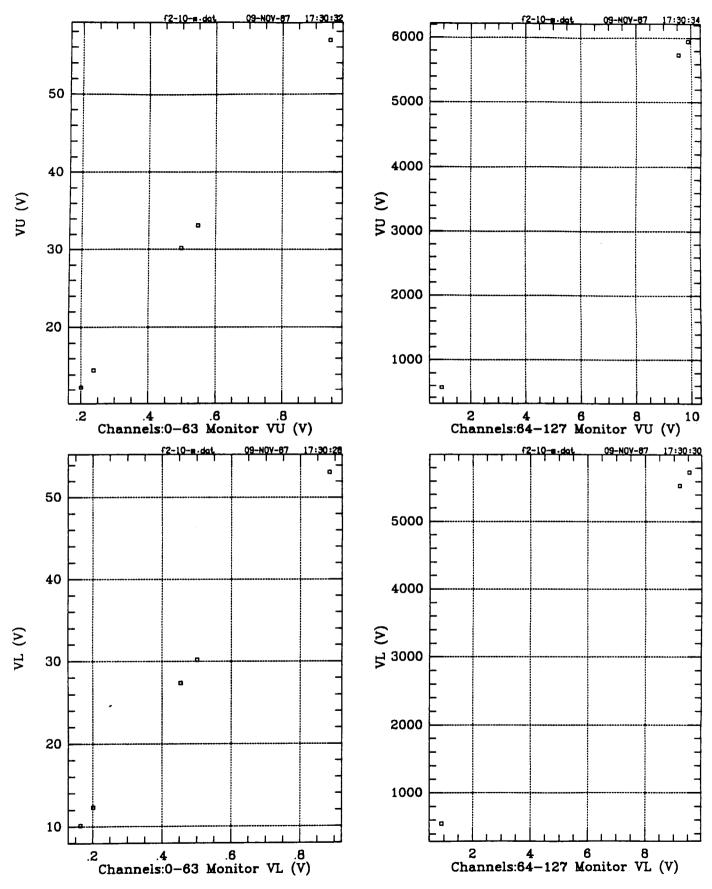
Flite:2 Temp:-5C Mode:M



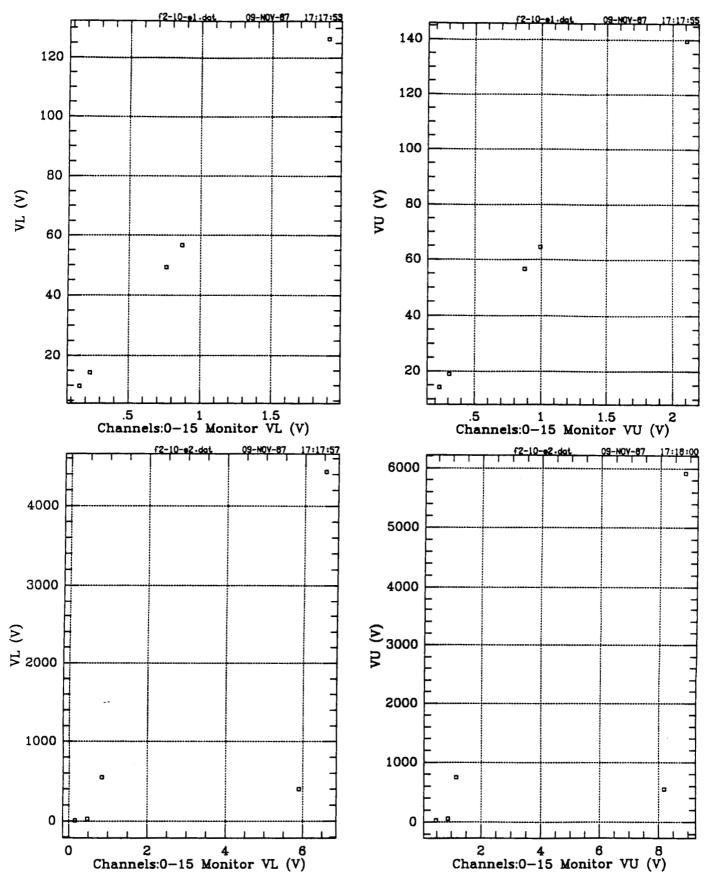
Flite:2 Temp:-5C Mode:E1 & E2



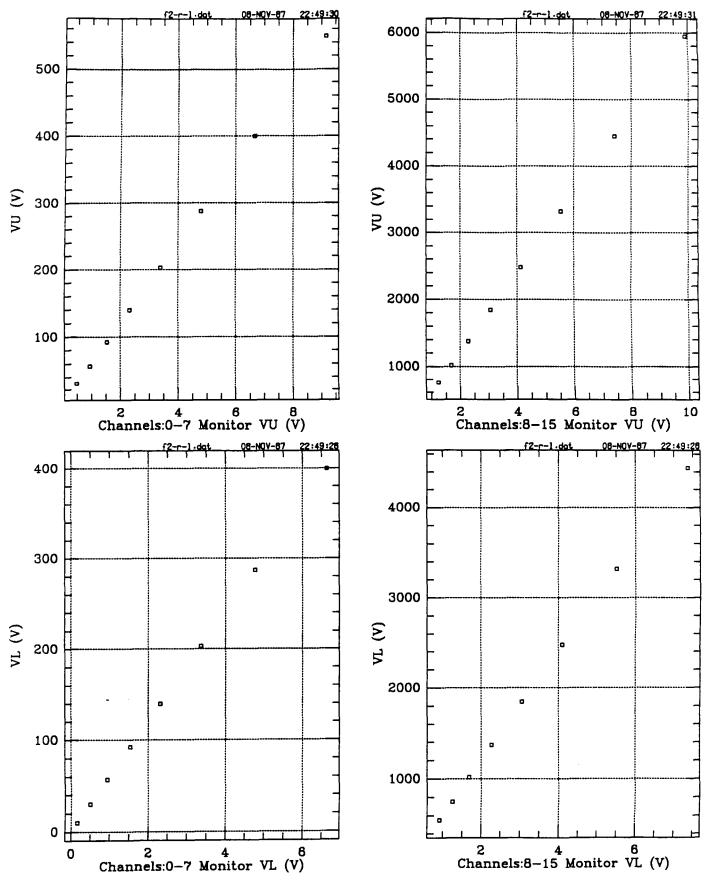
Flite:2 Temp:10C Mode:L



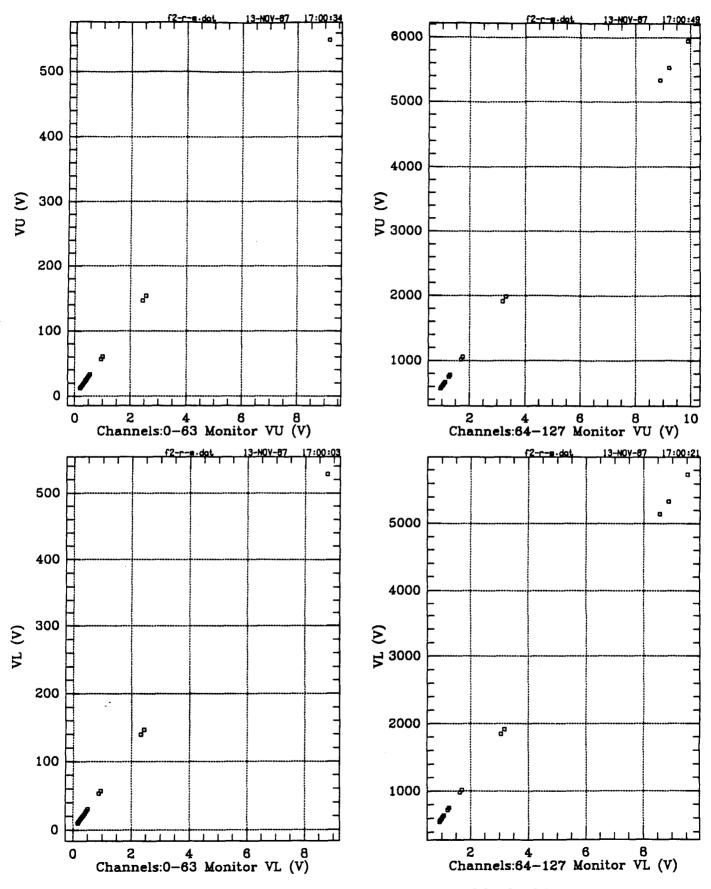
Flite:2 Temp:10C Mode:M



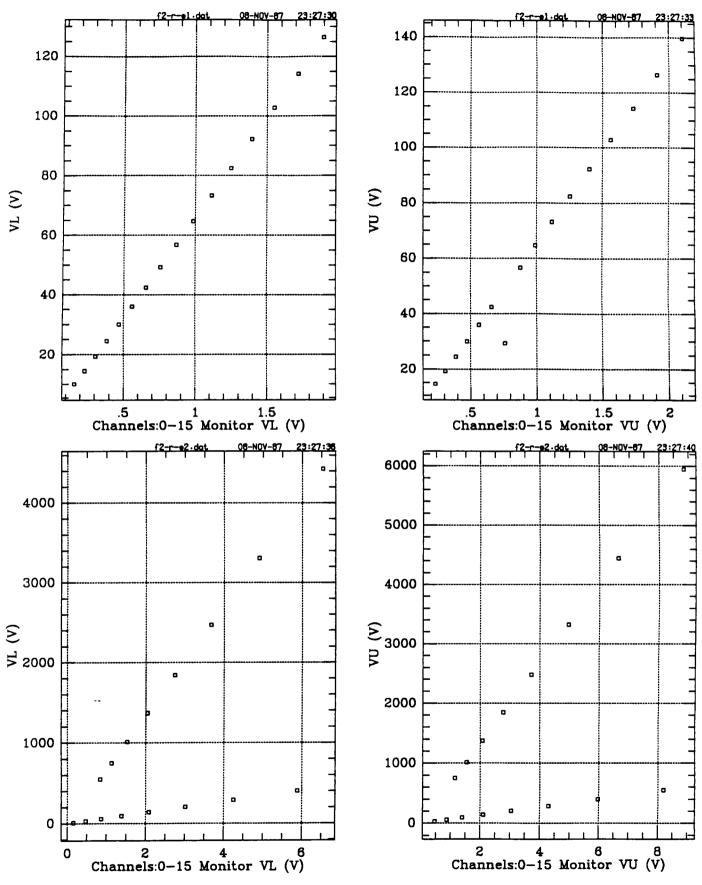
Flite:2 Temp:10C Mode:E1 & E2



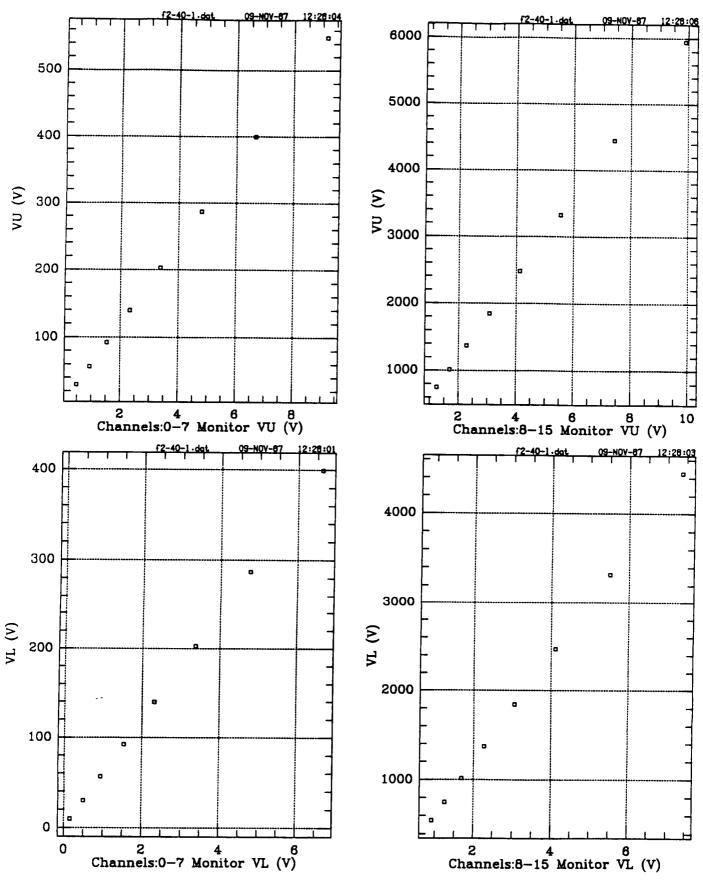
Flite:2 Temp:Room Mode:L



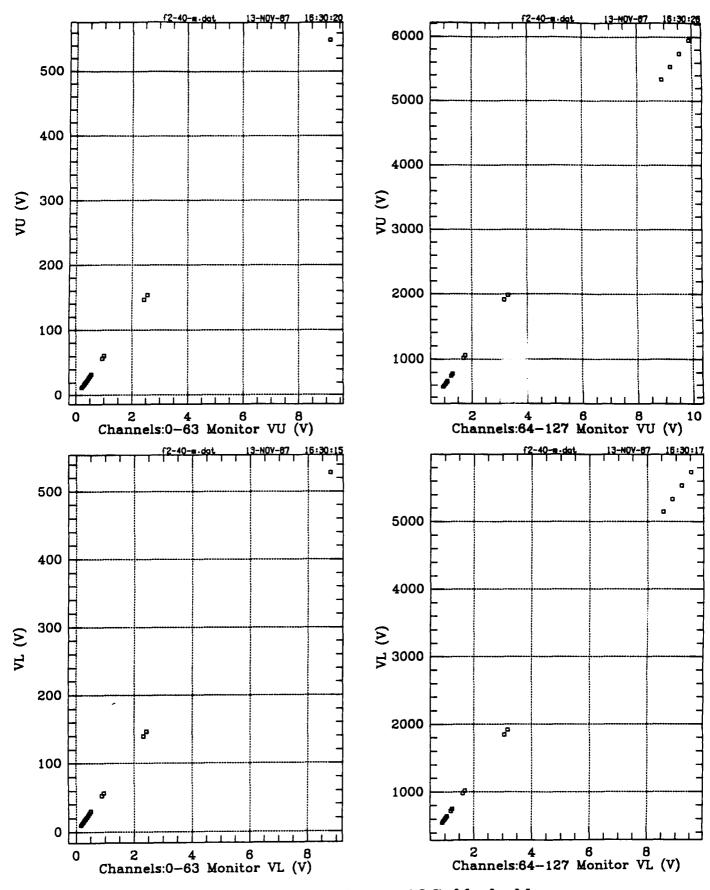
Flite:2 Temp:Room Mode:M



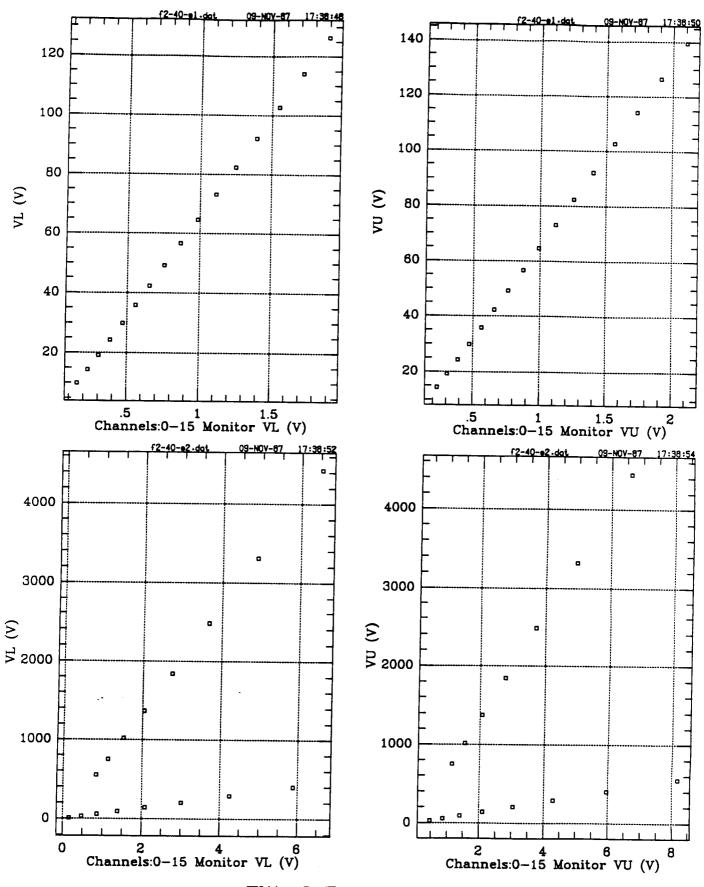
Flite:2 Temp:Room Mode:E1 & E2



Flite:2 Temp:40C Mode:L



Flite:2 Temp:40C Mode:M



Flite:2 Temp:40C Mode:E1 & E2

```
¢
            DNS-CODE.F analyses the PLS Prototype data.
 С
 С
            Author: Ognen Nastov, MIT undergraduate, Nov 1987
 С
              C
           leastsq does a least square approximation
 c
                     and minimizes the round-of errors.
 С
                     n = \# \text{ of } x - y \text{ pairs}
 c
                     A = (1 / sum(t^{**2})) * sum(t^{*}y)
 c
                     B = (sum(y) - A*sum(x)) / n
 С
                     where t(i) = x(i) - sum(x) / n
           subroutine leastsq (filename, depth,
                     a, b, sqd)
           integer depth, dn
           real a, b, mv, x, y, sumx, sumy,
                     t(120), u(120), v(120), sumtsq, sumty, sqd
           character*8 filename
           sumx = 0
           sumy = 0
           sumtsq = 0
           sumty = 0
           open (1, file=filename, form='formatted')
           rewind (1)
           do 1010 counter = 1, depth
                    read (1, *) dn, mv
                     x = 255 - dn
                     y = log(mv)
                     sumx = sumx + x
                     sumy = sumy + y
                     u(int(counter)) = x
                     v(int(counter)) = y
 1010
                    continue
          do 1020 i = 1, depth
                    t(i) = u(i) - sumx / depth
                    sumtsq = sumtsq + t(i)*t(i)
                    sumty = sumty + t(i)*v(i)
1020
                    continue
          a = sumty / sumtsq
          b = (sumy - a*sumx) / depth
          call sqdev (a, b, depth, u, v, sqd)
          close (1)
          return
          end
C
          Sqdev calculates the square deviation
                    by definition.
          subroutine sqdev (a, b, n, u, v, sqd)
          integer n
          real a, b, u(120), v(120), sqd
          sqd = 0
          do 2000 i = 1, n
                    sqd = sqd + (a*u(i) + b - v(i))**2
2000
                    continue
          sqd = sqd / n
          return
          end
          The MAIN program body.
C
С
          It produces one line of output for each input file.
          The program uses a special driver file
C
C
                    dns-driver.dat.
          integer pairs
          real a, b, c1, c2
          character*8 filename
          character*4 mvr
          open (2, file='dns-driver.dat', form='formatted')
```

```
open (3, file='dns-output.dat', form='formatted')
            rewind (2)
            print *, 'Creating file: ', 'dns-output.dat', '...'
           read (2, *) filename, mvr, pairs
print *, 'Processing file: ', filename, '...'
call leastsq (filename, pairs, a, b, sqd)
50
            c1 = exp(b)
            c2 = a
            write (3, fmt=200) filename, mvr, c1, c2, sqd, pairs
100
            if (filename .ne. 'pe22.dat') go to 50
            close (2)
            close (3)
            print *, 'File: dns-output.dat created.'
200
            format (a8, tr2, a4, tr2, g12.6, tr2, g12.6, tr2,
                        g11.6, tr2, i3)
            end
```

```
С
           MVS-CODE.F analyses the PLS calibration data for both flites.
 С
 С
           Author: Ognen Nastov, MIT undergraduate, Nov 1987
 С
 С
           leastsq does a least square approximation
 С
                    | sum(x^{**}2)A + sum(x)B = sum(xy)
 c
                    | sum(x)A + nB = sum(y)
 С
                     where n = \# of x-y pairs
           subroutine leastsq (filename, voltrange, startline, endline,
                     a, b, sqd, depth)
           integer channel, startline, endline, skip, depth
           real a, b, mvu, mvl, vl, vu, hvdcout, x, y, sumxsq, sumx, sumxy,
                    sumy, sumysq, sqd
          character*6 voltrange
          character*12 filename
          sumxsq = 0
          sumx = 0
          sumxy = 0
          sumy = 0
          sumysq = 0
          open (1, file=filename, form='formatted')
          rewind (1)
          skip = startline - 1
          do 500 counter = 1, skip
                    read (1,*) channel, hvdcout, mvu, mvl, vl, vu
500
                    continue
          depth = endline - startline + 1
          do 600 counter = 1, depth
                    read (1, *) channel, hydcout, mvu, mvl, vl, vu
                    if (voltrange .eq. 'lower') then
                              x = mvl
                              y = v1
                    else
                              x = mvu
                              y = vu
                    endif
                    sumxsq = sumxsq + x*x
                    sumx = sumx + x
                    sumxy = sumxy + x*y
                    sumy = sumy + y
                    sumysq = sumysq + y*y
600
                    continue
          call solvesys (sumxsq, sumx, sumxy, sumx, depth, sumy,
                    a, b)
          call sqdev (a, b, depth, sumx, sumy, sumxy,
                    sumxsq, sumysq, sqd)
          close (1)
          return
          end
C
          lsq2 does a least square approximation
c
                    and also minimizes round-of errors
C
                    n = # of x-y pairs
                    A = (1 / sum(t^{*2})) * sum(t^{*y})
С
                    B = (sum(y) - A*sum(x)) / n
¢
c
                    where t(i) = x(i) - sum(x) / n
         subroutine lsq2(filename, voltrange, startline, endline,
                    a, b, sqd, sqda, sqdb, cov, depth)
         integer channel, startline, endline, skip, depth
         real a, b, mvu, mvl, vl, vu, hvdcout, x, y, sumx, sumy,
                   t(20), u(20), v(20), sumtsq, sumty, sqd,
                   sqda, sqdb, cov, del, sumxsq
         character*6 voltrange
         character*12 filename
         sumx = 0
```

```
sumy = 0
            sumtsq = 0
           sumty = 0
           sumxsq = 0
           open (1, file-filename, form-'formatted')
           rewind (1)
           skip = startline - 1
           do 1000 counter = 1, skip
                     read (1, *) channel, hvdcout, mvu, mvl, vl, vu
 1000
                     continue
           depth = endline - startline + 1
           do 1010 counter = 1, depth
                     read (1, *) channel, hvdcout, mvu, mvl, vl, vu
                     if (voltrange .eq. 'lower') then
                               x = mvl
                               y = vi
                     else
                               x = mvu
                               y = vu
                     endif
                     sumx = sumx + x
                     sumy = sumy + y
                     sumxsq = sumxsq + x*x
                     u(int(counter)) = x
                     v(int(counter)) = y
 1010
                     continue
           do 1020 i = 1, depth
                     t(i) = u(i) - sumx / depth
                     sumtsq = sumtsq + t(i)*t(i)
                     sumty = sumty + t(i)*v(i)
 1020
                    continue
          a = sumty / sumtsq
          b = (sumy - a*sumx) / depth
          call sqd2 (a, b, depth, u, v, sqd)
          close (1)
          del = depth * sumxsq - (sumx)**2
          sqdb = sqrt (sumxsq / del * sqd * depth / (depth - 2))
          sqda = sqrt (depth / del * sqd * depth / (depth - 2))
          cov = -sumx / del * sqd * depth / (depth - 2)
          return
          end
          sqd2 calculates the square deviation by definition
C
C
                    sqd = (1 / n) * sum(Ax + B - y)**2
          subroutine sqd2 (a, b, n, u, v, sqd)
          integer n
          real a, b, u(20), v(20), sqd
          sqd = 0
          do 2000 i = 1, n
                    sqd = sqd + (a*u(i) + b - v(i))**2
2000
                    continue
          sqd = sqd / n
          return
          solvesys solves 2x2 linear systems using determinants
С
C
                    a1*x+b1*y=c1
С
                    a2*x+b2*y=c2
          subroutine solvesys (a1, b1, c1, a2, b2, c2, x, y)
          integer b2
          real a1, b1, c1, a2, c2, x, y, det, detx, dety
          det = a1*b2 - a2*b1
          detx = c1*b2 - c2*b1
          dety = a1*c2 - a2*c1
          x = \frac{detx}{det}
```

end

```
y = dety/det
            return
            end
 С
            sqdev calculates the square deviation expanding
 С
                      the sum:
 С
                      sqd = (1/n) * sum(Ax + B - y)**2
           subroutine sqdev (a, b, n, sumx, sumy, sumxy,
                      sumxsq, sumysq, sqd)
           integer n
           real a, b, sumx, sumy, sumxy, sumxsq, sumysq, sqd
           sqd = a^*a^*sumxsq + n^*b^*b + sumysq + 2^*a^*b^*sumx -
                      2*a*sumxy - 2*b*sumy
           sqd = abs (sqd / n)
           return
           end
 С
           The MAIN program body.
С
           It produces four lines of output for each input file.
           The program makes use of the lsq2 and sqd2 subroutines.
С
           It uses the file mvs-driver.dat to get the info
С
C
                     essential to analyse only the appropriate chunks
c
                     of data.
           integer stl1, edl1, stl2, edl2, pairsl, pairsu
           real al, bl, sqdl, sqdal, sqdbl, covl,
                     au, bu, sqdu, sqdau, sqdbu, covu
           character*6 voltrange
           character*12 filename
           open (2, file='mvs-driver.dat', form='formatted')
           open (3, file='mvs-output.dat', form='formatted')
          rewind (2)
          print *, 'Creating file: ', 'mvs-output.dat', '...'
           analyze the first channel range...
50
          read (2, *) filename, stl1, edl1, stl2, edl2
          print *, 'Processing file: ', filename, '...'
          voltrange = 'lower'
          call lsq2 (filename, voltrange, stl1, edl1,
                     al, bl, sqdl, sqdal, sqdbl, covl, pairsl)
          voltrange = 'upper'
          call lsq2 (filename, voltrange, stl1, edl1,
                     au, bu, sqdu, sqdau, sqdbu, covu, pairsu)
          write (3, fmt=200) filename, 'chr1', 'mvl-vl', al, bl,
                     sqdl, sqdal, sqdbl, covl, pairsl
          write (3, fmt=200) filename, 'chr1', 'mvu-vu', au, bu,
                     sqdu, sqdau, sqdbu, covu, pairsu
С
          analyze the second channel range...
          if (stl2 .eq. 0) go to 100
          voltrange = 'lower'
          call Isq2 (filename, voltrange, stl2, edl2,
                     al, bl, sqdl, sqdal, sqdbl, covl, pairsl)
          voltrange = 'upper'
          call Isq2 (filename, voltrange, stl2, edl2,
                     au, bu, sqdu, sqdau, sqdbu, covu, pairsu)
          write (3, fmt=200) filename, 'chr2', 'mvl-vl', al, bl,
                     sqdl, sqdal, sqdbl, covl, pairsl
          write (3, fmt=200) filename, 'chr2', 'mvu-vu', au, bu,
                    sqdu, sqdau, sqdbu, covu, pairsu
100
          if (filename .ne. 'f2-40-e2.dat') go to 50
          close (2)
          close (3)
          print *, 'File: mvs-output.dat created.'
200
          format (a12, tr2, a4, tr2, a6, tr2, f9.5, tr2, g12.6, tr2,
                    g11.6, tr2, g12.6, tr2, g12.6, tr2, g12.6, tr2, i2)
```

```
C
           MVS-TC-CODE.F
 С
 С
           Author: Ognen Nastov, MIT undergraduate, Nov 1987
 С
c
           Isq2 does a least square approximation
С
                      and also minimizes round-of errors
С
                      n = # of x-y pairs
С
                      A = (1 / sum(t^{**}2)) * sum(t^{*}y)
С
                      B = (sum(y) - A*sum(x)) / n
                     where t(i) = x(i) - sum(x) / n
           subroutine lsq2(filenames, filenum, voltrange, startlines,
                     endlines, a, b, sqd, sqda, sqdb, cov, totdep)
           integer channel, startlines(6), endlines(6), skip,
                     depth(5), curfile, totdep, filenum
           real a, b, mvu, mvl, vl, vu, hvdcout, x, y, sumx, sumy,
                     t(100), u(100), v(100), sumtsq, sumty, sqd,
                     sqda, sqdb, cov, del, sumxsq
          character*6 voltrange
          character*12 filenames(6)
          sumx = 0
          sumy = 0
          sumtsq = 0
          sumty = 0
          sumxsq = 0
          curfile = 1
          totdep = 0
500
          open (1, file-filenames(curfile), form-'formatted')
          rewind (1)
          skip = startlines(curfile) - 1
          do 1000 counter = 1, skip
                     read (1, *) channel, hvdcout, mvu, mvl, vl, vu
1000
                    continue
          depth(curfile) = endlines(curfile) - startlines(curfile) + 1
          do 1010 \text{ counter} = (\text{totdep} + 1), (\text{totdep} + \text{depth}(\text{curfile}))
                    read (1, *) channel, hvdcout, mvu, mvl, vl, vu
                    if (voltrange .eq. 'lower') then
                               x = mvi
                               y = vl
                    else
                               x = mvu
                               y = vu
                    endif
                    sumx = sumx + x
                    sumy = sumy + y
                    sumxsq = sumxsq + x*x
                    u(int(counter)) = x
                    v(int(counter)) = y
1010
                    continue
          close (1)
          totdep = totdep + depth(curfile)
          curfile = curfile + 1
          if (curfile .le. filenum) go to 500
          do 1020 i = 1, totdep
                    t(i) = u(i) - sumx / totdep
                    sumtsq = sumtsq + t(i)*t(i)
                    sumty = sumty + t(i)*v(i)
1020
                    continue
          a = sumty / sumtsq
          b = (sumy - a*sumx) / totdep
          call sqd2 (a, b, totdep, u, v, sqd)
          del = totdep * sumxsq - (sumx)**2
          sqdb = sqrt (sumxsq / del * sqd * totdep / (totdep - 2))
          sqda = sqrt (totdep / del * sqd * totdep / (totdep - 2))
          cov = - sumx / del
```

```
return
           end
 С
           sqd2 calculates the square deviation by definition
 c
                      sqd = (1/n) \cdot sum(Ax + B - y)^{**}2
           subroutine sqd2 (a, b, n, u, v, sqd)
           integer n
           real a, b, u(20), v(20), sqd
           sqd = 0
           do 2000 i = 1, n
                     sqd = sqd + (a*u(i) + b - v(i))**2
 2000
                     continue
           sqd = sqd / n
           return
           end
C
           The MAIN program body.
С
           It combines the files that are corresponding to the same
c
           temperature, and produces four lines of output per each
c
           combination. The program uses two driver files:
c
           mvs-driver.dat and mvs-tc-driver.dat. The lsq2 subroutine
C
           has been modified in order to be able to combine several
           files for analysis.
           integer stl1(6), edl1(6), stl2(6), edl2(6), pairsl, pairsu,
                     filnum, i
           real al, bi, sqdl, sqdal, sqdbl, covl,
                     au, bu, sqdu, sqdau, sqdbu, covu
           character*6 voltrange
           character*12 filenames(6), mfile, file
           open (2, file='mvs-driver.dat', form='formatted')
          open (3, file='mvs-tc-out.dat', form='formatted')
          open (4, file='mvs-tc-driver.dat', form='formatted')
50
          i = 0
          read (4, *) mfile
100
          i = i + 1
          read (4, *) filenames(i)
          if (filenames(i) .ne. '*') go to 100
          filnum = i - 1
          do 200 i = 1, filnum
                     rewind (2)
300
                     read (2, *) file, stl1(i), edl1(i),
                               stl2(i), edl2(i)
                    if (file .ne. filenames(i)) go to 300
200
                    continue
          print *, 'Processing master-file: ', mfile, '...'
          voltrange = 'lower'
          call lsq2 (filenames, filnum, voltrange, sti1, edl1,
                    al, bl, sqdl, sqdal, sqdbl, covl, pairsl)
          voltrange = 'upper'
          call lsq2 (filenames, filnum, voltrange, stl1, edl1,
                    au, bu, sqdu, sqdau, sqdbu, covu, pairsu)
          write (3, fmt=2000) mfile, 'chr1', 'mvl-vl', al, bl,
                    sqdl, sqdal, sqdbl, covl, pairsl
          write (3, fmt=2000) mfile, 'chr1', 'mvu-vu', au, bu,
                    sqdu, sqdau, sqdbu, covu, pairsu
          analyze the second channel range ...
          if (stl2(1) .eq. 0) go to 500
          voltrange = 'lower'
          call lsq2 (filenames, filnum, voltrange, stl2, edl2,
                    al, bl, sqdl, sqdal, sqdbl, covl, pairsl)
```

voltrange = 'upper'

```
call lsq2 (filenames, filnum, voltrange, sti2, edl2,

au, bu, sqdu, sqdau, sqdbu, covu, pairsu)
write (3, fmt=2000) mfile, 'chr2', 'mvl-vl', al, bl,
sqdl, sqdal, sqdbl, covl, pairsl
write (3, fmt=2000) mfile, 'chr2', 'mvu-vu', au, bu,
sqdu, sqdau, sqdbu, covu, pairsu

if (mfile .ne. 'f2-e2.dat') go to 50
close (2)
close (3)
print *, 'File: mvs-tc-out.dat created.'

2000 format (a12, tr2, a4, tr2, a6, tr2, f9.5, tr2, g12.6, tr2,
g11.6, tr2, g12.6, tr2, g12.6, tr2, g12.6, tr2, end
```

MEMORANDUM

Massachusetts Institute of Technology Center for Space Research

September 24, 1987

VOYAGER MEMORANDUM # 161:

From:

Ralph L. McNutt, Jr. Arm

To:

Voyager Internal

Subject: Modulator Calibrations (Modcal or MVM): Interpretation

NORMAL OPERATION

As part of the routine calibration sequence on the Voyager Plasma Science (PLS) experiment, there is a digitized readout of the low voltage signal which is proportional to the potential on the modulator grids. This is accomplished via a set of Modulator Voltage Monitors; these measurements are referred to by MVM on Summary or EDR tape logs. In many of the engineering notebooks they are referred to as "Modcal" measurements or mode (as compared to "Curcal" or current calibration measurements. In producing the modulator voltage, the voltage is stepped through one decade from 60 to 600 volts and then through the same steps with a extra gain of × 10 switched into the circuit to sweep from 600 to 6000 volts. To this voltage is added an offset of 50 volts. Hence, the L and M modes sweep from +10 V to +5950 V and the E2 mode sweeps from -10 V to -5950 V (the E1 mode sweeps from -10 V to --140 V by using a different step size). Thus, the true voltage ranges across 2.8 decades.

The voltage monitors measure a voltage which is a constant fraction of the voltage swept which does not include the factor of 10 gain change. The monitors measure a voltage between 0.1 and 10 volts which is then input into a fast A/D converter. This voltage is then converted to a binary number from which the highest order bit is discarded. Thus, as the low voltage sweeps between 0.1 and 1.0 the digital output sweeps from 0 to 255; as the voltage sweeps from 1.0 to 10.0 volts, the output again sweeps from 0 to 255, although retention of the highest order bit would give a digital output from 256 to 511. Hence, the voltage monitor output can correspond to 4 orders of magnitude although, again, the factor of 10 gain change is not explicitly incorporated in this measurement. To know which decade is actually being read out, one must either rely on a "proper sequence" (the case for nominal operation for which the MVM readout presumably yields voltages close to the nominal values) or an "educated guess" (for interpreting the MVM readouts from the PLS instrument on Voyager 1 after the failure).

NOMINAL VOLTAGE LEVELS

The nominal conversion between channel number (or "step number") is employed in all analysis (both in the VGRANL and MJSANL software packages). The conversion between channel number and voltage is discussed in *Bridge et al.* [1977]. Let n be the channel number, which can take on values of 1 to 16 for the E1, E2, and L modes and 1 to 128 for the M mode. Let M be an integer with values of 8 for the E2 and L modes, 32 for E1 and 64 for M. Then the potential ϕ_n at the lower edge ("bottom") of channel n (also referred to below as $V_{L, HV}$), which is equal to the voltage at the upper edge ("top") of channel n+1 (also referred to below as $V_{U, HV}$), (the upper edge potentials follow from considering "channel" 129 for the M mode and 17 for the other modes), is given by

$$\phi_n = 60 \cdot 10^{n/M} - 50 \tag{1}$$

where ϕ_n is in volts. This formula only yields magnitudes, of course, the actual potentials in the E1 and E2 modes being negative.

It is important to note that the 50 volt offset makes the channel spacing only quasilogarithmic; at lower channel numbers, the channel widths are larger than if they were logarithmically spaced.

NOMINAL FAST A/D VOLTAGE CONVERSION

Information on the analog-to-digital converter is contained in Anton Mavretic's lab note-book labeled book 2, number 254 (starting date of July, 1974). On page 142 (dated 7/25/75), we find for analog voltage ν running from 0.1 to 10, the digital count number N running from 0 to 127. Anton gives the constitutive relation as

$$v = V_{REF} e^{-\frac{(127 - N)T}{\tau}} \tag{1}$$

and values $V_{REF} = 10$ V, $T = f_{AD}^{-1} = 1/57.6$ kHz = 17.36 μ s, $\tau = 482.55$ μ s. Transforming to base 10, this yields

$$v = 10 \times 10^{\frac{(127 - N)}{64.00008}} \tag{2}$$

where the denominator in the exponent is usually approximated as the integer 64.

On page 143, formulas are given for the fast A/D conversion. Anton lists

$$v = V_{REF} e^{\frac{-(255 - N)T}{\tau}}, \quad 1.0 < v < 10.$$
 (3a)

and

$$v = V_{RFF} / 10 e^{\frac{(255 - N) T}{\tau}}, \quad 0.1 < v < 1.0.$$
 (3b)

with $T = f_{fast AD}^{-1} = 1/230.4$ kHz = 4.34 μ s, $\tau = 482.55$ μ s. Transforming to base 10, this yields the combination

$$v = 10 \times 10^{\frac{(255 - N)}{256}}, \quad 1.0 < v < 10.$$
 (4a)

and

$$v = 10^{-\frac{(255 - N)}{256}}, \quad 0.1 < v < 1.0.$$
 (4b)

Although not explicitly stated, these are apparently the nominal, rather than measured,

NOMINAL MONITOR OPERATION

In the usual MVM mode, the data numbers (DN) produced by running the low voltage monitor outputs through the fast A/D converter are returned as a function of channel number. In the L and M modes, the DNs corresponding to V_L are returned in the space occupied by A cup plasma measurements in the usual plasma measurement mode; similarly, the DNs corresponding to V_H are returned in the space occupied by the B cup plasma measurements. The C cup and D cup contain currents corresponding to normal plasma currents but with DN values obtained from the fast A/D converter. Hence, for the L and M modes, there is a measure of the contiguity of neighboring channels (gaps and/or overlaps in coverage).

For the E1 and E2 modes, there are only 16 slots available in the data sequence for each mode, so compromises were made in deciding which DN values would be included in the telemetry stream. For odd channel numbers (counting from 1 to 16), the DN corresponding to V_L is returned. For even channel numbers, the DN corresponding to V_U is telemetered. Hence, both absolute value and contiguity are checked, but only for every other channel. For example, there are MVM measurements for V_{L1} , V_{U2} , V_{L3} , V_{U4} , V_{L5} , etc., but there is no calibration information for the boundaries between channels 1 and 2, 3 and 4, etc.

In nominal operation, note that we should have $V_{U,n} = V_{L,n+1}$. Indication of where the V_U s and V_L s come in the data is given in the VOYPRT appended to Voyager Memorandum 158 as Figure 6.

RELATIONSHIP BETWEEN MODULATOR POTENTIAL AND MONITOR VOLTAGES

Figure 1 (from J. Binsack) shows a simplified block diagram of the high voltage modulator circuit for the PLS instrument; indicated on the figure is the location of the suspected failed circuit in the Voyager 1 PLS instrument. The low voltage monitor voltages are measured at the point indicated with the arrow and labeled " $V_{fb} = CAL$. This low voltage is (nominally) directly proportional to the high voltage applied to the modulator grids (at least in the linear regime of the amplifiers). The DC gain of the Cockcroft-Walton amplifiers ("C. W.") and the AC gain of the transformer in the feedback loop are unknown as of this writing, so a theoretical value of the proportionality factor is not known (but could be derived from the appropriate circuit diagrams, J. Binsack, private communication, 1987). Data shown in Appendix A (see below) suggests that this factor is ~ 60 .

The subcontractor responsible for the high voltage power supply, Matrix Research and Development Corporation, measured both the voltage to ground from the modulator grid leads and the low voltage monitor outputs for all three modulators (on SN001, SN002, and SN003) for all channels in all modes. Work has begun to combine this information with other information to develop an algorithm to link the measured DNs in the MVM mode with the actual modulator potential. It is important to note that all modulator potential measurements were actually made with high impedance probes to the modulator grid leads, terminated with capacitances to approximate the electrical characteristics of the grids themselves (R. Butler, private communication, 1987). In no case were potential measurements made on the grids themselves with the grids in place in the cups; this is not possible as a probe cannot physically be

inserted into the assembly.

Before the PLS instruments were to delivered to JPL for integration with the Voyager spacecraft, extensive calibration tests were run at the MIT Laboratory for Space Experiments using the Bench Checkout Equipment (BCE). The modulator was stepped through all channels in all modes and the DNs (or "decimal counts") were recorded as a function of step number, equal to the channel number minus one (channel 1 corresponds to step 0).

In Appendix A, the reference counts are listed as a function of step number for each mode (labeled for the prototype rather than for one of the flight units). Corresponding voltages from the voltage monitors are also given. Note that these are the counts measured with the BCE. For example, the nominal value of $V_{L, HV}$ for step 0 is +10 V in L and M modes and -10 V in E1 and E2 modes. The reference counts for the L, E1, E2, and M modes are, respectively, 54, 48, 50, 48. The fraction values for V_L are, presumably, the measured low voltage monitor outputs (they are not nominal values as the nominal value should be the same in for all of these). The applicable equation relating the monitor voltages and the reference counts is (4b). However, applying (4b) to values of 0.172, 0.163, 0.166, 0.163, yields DNs of 59.3, 53.3, 55.3, and 53.3, respectively. This suggests that the theoretical A/D algorithms are off (if the reference counts and monitor voltages were really measured simultaneously). Note that (4b) is off by about a factor of $10^{5/256} = 1.046$, but not quite.

The agreement is better at the other end of the scale for V_U of step 15 of E2 and L and step 127 of M, the counts are 248 and the monitor voltage is 9.314 V. Using 9.314 volts and equation (4a) yields a DN of 247.1. Again, if the counts and monitor voltages were measured at the same time (which is not known), there is some nonlinearity in the A/D converter, not currently accounted for. A spot check suggests that a simple DC offset voltage also does not account for the discrepancy.

I have searched through all of Anton's notebooks stored in Herb's office and through all of the files in N-52 and have not been able to locate any documentation (other than that mentioned above) on the performance of the A/D converter. To put all of this in perspective, at the higher voltages in the M mode, the reference counts for V_U and V_L are separated by 4 DN. This implies that a determination of the true potentials on the modulator grids to an accuracy of better than 1% should, in principal, be possible.

Attached as Appendix B are similar modulator calibration data from the Flight 1 unit (on Voyager 1, i.e., SN002). Most of the measurements are dated 4/22/77, less than 5 months before the launch. Unfortunately, simultaneous high voltage, monitor voltage, and DN were not recorded. It is worth noting that for step 127 of the M mode, the measured value of V_U was 6010 volts, as compared to a nominal value of 5950 volts, a deviation from nominal of 1%. This suggests that such deviations are not uncommon.

MODULATOR VOLTAGES FOR THE VOYAGER 1 PLS INSTRUMENT AFTER THE FAILURE

The assumed circuit failure on the Voyager 1 PLS instrument pegged the value of V_L at some value greater than 6000 V, and caused the values of V_U to increase with step number, but in a spurious way (J. Binsack, private communication, 1987), i.e., the phase of the modulated current is shifted 180°. Hence, the solar wind can no longer be detected in the normal plasma mode because the current is detected synchronously, and the failure introduced the incorrect phasing.

If the value of V_L is pegged to a large value, then the solar wind is always excluded from the detector for half of a measurement. If the value of V_U is low enough, then the solar wind should be admitted for the other half, unless V_U steps to a large enough value to also exclude the solar wind.

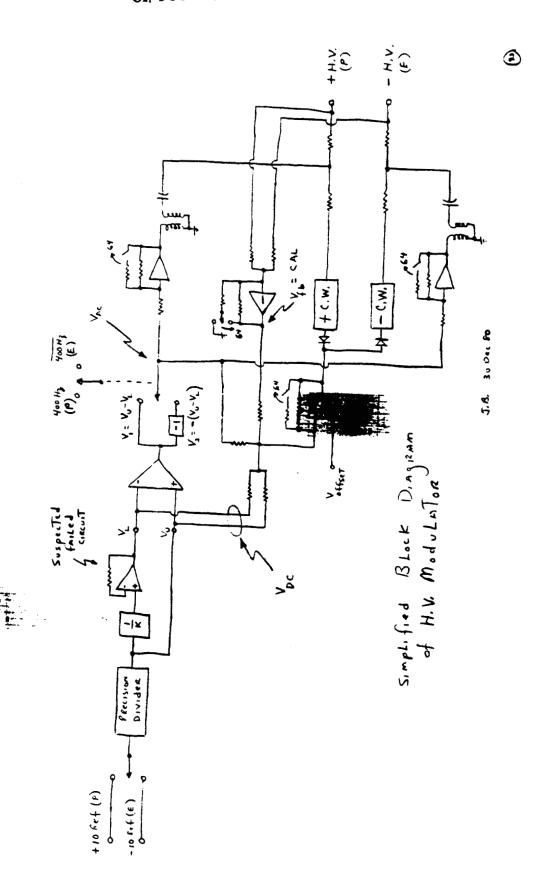
The DC return measurements from the Voyager 1 instrument after the failure show changes in all 16 channels which vary with time; this presumably gives some measure of the solar wind flux (see Voyager Memorandum 157). There is a "break" in the DN numbers in the DC return mode above channel 8, suggesting that V_U for the first 8 channels (in the L mode) is always low enough to allow the solar wind access to the collector plate. The DNs decrease for the top 8 channels suggesting that more of the solar wind is gradually being excluded, but the lack of variation in this pattern could mean that this is another instrumental effect instead. The interpretation is also complicated by the fact that there is a factor of 10 gain change internally in going from the voltages for channel 8 to those of channel 9, so the break at this point may actually be related to this change.

From the L mode spectrum in Figure 6 of Voyager Memorandum 158 (referred to previously), the MVM data numbers change from 190 to 93 for the first 8 channels of the L mode (at 1980-346/0103:23.735) with a "fold" occurring between channels 2 and 3. If the DNs can be interpreted as before the failure, then the fold could occur at ~6, 60, 600, or 6000 V. The value of 6000 V must be excluded on the basis of the detection of the solar wind. At channel 8, the DN of 93 could be ~14 or 140 V; higher values are again excluded because the solar wind is detected.

In the top 8 channels, the DNs run from 90 to 136. If no "folds" are present (and none are apparent), this could correspond to ~140 V to 210 V or some multiple of 10 times these limits. These potentials would allow the solar wind to be admitted in all channels, but for speeds of 400 km/s, similar to those detected by Voyager 2 at these distances, no decrease in DC current with channel number should be present. Multiplying the limits by a factor of 10 would exclude the solar wind from the top channel, unless its speed exceeded ~600 km/s, and speeds of this magnitude were not detected just prior to the failure, so something is not consistent.

To understand the post-failure measurements by the instrument on Voyager 1, a more detailed investigation is clearly required. Such an investigation is now underway.

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APPENDIX A

 ${\tt MVM} \ {\tt Measurements} \ {\tt for} \ {\tt Prototype}$

PLS-PROTOTYPE HIGH VOLTAGE MONITORS

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DEC. COUNTS

L-Mode

S.C. = 960 ms

	DDC. C	001115				.000	.:		5	.C. =	960 n	IS	
Step	Reference +V _L	1	+VL EV]	+Vu EV]									
0	054			0.466								-	
1	173	1		0,892									
2	243	1 1		1.441									_
3	041	224		2169									
4	088	•		3.150									
5	130			4.455							:		_
6	169			6.189	l								
7	نکن <i>+</i> 206	238	1,413	8,522									<u> </u>
8	238 Kaul	015+255	0.894	1.175		·							-
9	017 425			1,589					٠.		·. •		
10	051	083	1618	2,150	•	·							
11	084	116	2.167	2.882	٠	•							_
12	118	149	2,934	3.864						·			
13	151	182	3.934	5.181					·				
14	184	215	7.274	6,947				·		:			
. 15	216	ر آدنــ 248											
				:									
							·	No.	1 - 71 -	1 11 JAC	:		
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PLS-PROTOTYPE HIGH VOLTAGE MONITORS

DEC. COUNTS

El-Mode

		00.115				1.000).C. =	960	ms	
Step	Reference -VL	ce Counts	-VL CONV.	-Va conv	ارون اور مارون اورون								
0	048		0.163		3.9%			1				·	
1		121		0.313				1					
2	121		0.313										
. 3		170		0483	3.97,		1				·		
4	170		0.483		3.97			1.					
5		209	·	0.683	1				1		<u> </u>		-
6	208		0.677		4.89,					1 *		·	-
7		241		0.908	4.3%							1	
8.	241		0.908		* .				-				
9	"	014		1.164									7.
_ 10	013		1.154		6.0%								
11		039		1.454	- 1	-							
12	039		1.454		5.9%								
13		063	-	1.700									
14	063		1.800	·	5.9%					•		·	
15	<i>i</i>	086		2.208							·		
·		·				-							
		·							·				·
											:	·	
					·						: :		
		·									·		
												·	
6													
						•							;-

PLS-PROTOTYPE HIGH VOLTAGE MONITORS

DEC. COUNTS E2-Mode S.C. = 960 msReference Counts -VL -Vu Lep -V_[] -VL [٧] [v] 0.166 0 050 0.900 1 240 2 0.908 241 . 2.208 3 086 4 086 2.208 4.494 5 166 6 167 4.535 239 +258 8.598 **7**. 0.876 237 8 1.603 9 050 +255 1.603 10 050 2.908 1. 117 2.908 12 117 5.227 13 183 5,227 183 14 15 248 9.314

PLS-PROTOTYPE HIGH VOLTAGE MONITORS

DEC. COUNTS

M-Mode

S.C. = 960 ms

	•	DEC.	COOMIS											-
(Step	Reference +VL	ce Counts	+VL [V]	+V4 [V]	-								
	0	048	071		0,200			14/2	1.				·	
	1	070	089		1			<u>-</u>)	-0.12					
	2	089	106	0,253				1.3	11.22	5				
-	3	106	121	ł	0,313	·		5) 5	->0.26	2				
	4	121	134		0.351				·		-:	٠		
	- 5	134	147	0,351										
	. 6	147		0,394	1									·
	7	159 .	169	0.438	0.479							- 1 · 1		<u> </u>
	8	170:	1.80	0.483	0,528	•					·			·
	. 9	180	190	2 ,528	0.577	·	·							
	10	190	199	0.577	0.625	٠	·							
	11	199		0,625					·					
	12	208	217	0.677	0,734		·							
	13	217	225	0.734	0,788									
	14	225	233	0,783										
	15	233	240	0.846	0,900	· .	·					•		
	16	241	248	0,908	0,966						· :			
	17	248		0,966					÷					
i	18	255-	-006+257					ż	٠					
	19	006+255	1	1.084		·						•		
	20	013	020	1.154	1,228						·			
	21	020	026	1,28			·					·		
	22	027	033		1,377							•	·	
3	23	033	039	1,379										
	24	039		1.454	1,534									
	25	045	051 +255				-		·					
_														

PLS-PROTOTYPE HIGH VOLTAGE MONITORS

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DEC. COUNTS

M-Mode

Step		e Counts	+VL	+V4								
	+v _r	+V _U	CVI	[V]	<u> </u>	<u> </u>	ļ	<u> </u>	<u> </u>			
26	051+255	057 <u>+ کې:</u>	1.618	1,706								
27	057	063	1.706	1,800				<u> </u>				
28	063	069	1.800	1,398		_		·			·	
. 29	069	074	1.898	1,984								
30	075	080	2,002	2,093					· -			
31	080	086	2.093	2208								
32	086	091	2,208	2,308								
33	091	096	2,308	2413								
34	096	102	2,413	2545	•							
35	102	107	2,545	2.661							: •	
36	107	112	2,661	2,782		·					•	:
37	112	117	2.782	2908		-						
38	117	100	2,908									
39	123	127	3,067	3.178			·					
40	128	132	3.207	3,323						:		
41	133	137	3,352	3,473				·			·	
42	138	142	3,504	3,631		·				:		
43	143	147	3,664	3.7%				:				
44	147.	152	3.796	3,969	:		:	·				
45	152		3,969								:	
. 46	157	162		4,338							÷	
47	162	166	4,338	4,494								
48	167	171		4.679	i							
49	171	176		4.912						·		
50	176	180	4,912	5,090								
51	181,22	185	5.135	5.321								

PLS-PROTOTYPE HIGH VOLTAGE MONITORS

DEC. COUNTS

M-Mode

•											J 0 0 1		
Step	Reference +VL	e Counts	+V2 [V]	+V4 [V]									T
52	185:	1904255		5.563								·	t
53	190	,		5:764	l								T
54	195	199	5,816	6,026							-		Γ
55	199	203	l .	6,244									Γ
56	204		ì	6.528							•	_	Γ
57	208	212	6,528	6.764									
58	213	217	6,824	7.07/								-	Γ
59.	217	221	7.071	7.327	·						•		Γ
60	222		7,392					. :			_		T
61	226		7,660			·			÷				
62	230			8,248								·.	
63	كزيه 235	239+25	8,298	8,578	,	•							Ī
64	237 Rg!		0.876										r
65	241		0,908			-							Ī
66	246		0,949										T
67	250	أعرث , 254				·					•		r
68	254				·	·			:				Ī
69	003+255	227	1.056					:		. :			
70	007		1,094				Ť			·	·		r
71	011		1,134								:		
72	016		1,185								:		
73	020		1.228								:		
74	024		1,273		·		·						
75	028		1,319									·	
76	033	037	1,379										
77	037	041+255				-							r
			77201	, , , , ,	1			<u>'</u>					_

HIGH VOLTAGE MONITORS

	DEC COU	INTS			M-M	ode			s.	c. =	960 m	S
Step	Reference +VL	e Counts	+V2 [V]	+V4 [v]								
78	041+255	0457255			_							
79	046	050		1,603	·							
80	050	054	1.603									•
81	054	058	1	1.721								•
82	058	062		1.784					·		٠	
83	062	067	1,784	1.865						•		
84	067	071	1,865	1.932		-			. :			
85	071	075	1,932	2.002								
86	075	079	ZOZ	2075	•				•			
87	079	083	2075	2,150							•	
88	084	088	2.169	2.247								
89	088	092	2,247	2,329						1		
90	092	096	2,329	2413						·		
91	096	100	2,413	2.500						·		
92	100	104	2,500	2591			٠			:		
93	104	108	2,591	2684				·				
94	109	112	2.708	2782								
95	113	117	2806	2908				:		. :		
96	117	121	2.408	3.013								
97	121	125	3.013	3.122						· .	:	
98	125	129	3,122	3.235								
99	129	133	3,235	3.352								
100	133	137	3,352	3,473							·	
101	137	141	3.473	3,597							-	
102	142	146	3,63/	3.763							}	
103	146 / 35	150	3.763	3.879			1	1		1		

DEC. COUNTS M-Mode S.C. = 960 msT+V4 +1/ Reference Counts Step +V_[] $+V_{L}$ [V] [V] 154 +25 3,899 4,040 150+25 4.040 4.186 158. 4,186 4,338 4,338 4,494 4.494 4.657 4.657 4.826 4.869 5.000 5.045 5,227 5,227 5.417 5.417 5.613 5,613 5,816 5.816 6.026 6.026 6.244 6.244 6.470 6.470 6.704 6,704 6,947 6.947 7.193 7,198 7,525 7,525 7,797 7,797 8,079 5,079 8.372 8,3728,675

244 +25-

244 1=14 8,675 8.489

248 +25- 8,989 9,314

APPENDIX B

MVM Measurements for Flight 1 (SN 002)

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OF POOR QUALITY SEATS 30 1 1/20/76 PLS-PROTOTYPE FI Tested with MIT HIGH VOLTAGE MONITORS made h.v. tester DEC. COUNTS L-Mode Ref. S.C. = 960 msReference Counts $\sqrt{}$ Voc V 'scep $\sqrt{\mathbf{u}}$ V_{\perp} Vi V_{ν} Vu +Vr1 70 054 0 166 30D 10. 1 173 239 93.35 56.7 30.0 55 28 124,5 92.3 50.7 2 243 038 92 54 90 56 166.01 139.7 192.3 041 3 084 138 90 221.38 203.0 139.7 088 202 138 135 126 **200**. 287 295.21 287.4 203.0 5 130 165 202 393.67 399.94 287.4 401 6 169 202 288 50.0 349.9 7 . 206 238 552 401 750.1 550.0 8 238 015 752 749 552 5-49 . 9 017 049 1017.0 750.1 1016 751 1372.8 1017.0 10 051 083 1374 1520 (. 1847 13728 1848 084 :76 116 16527 IRL 12 2480, 1847 2492 30 118 149 2493 1859 114 ~~ 1 13 151 . 182 3324 2480. ÷-55 12 449/3351 14 184 215 4449. 3324. 5030 4481 4462 5980 15 216 248 4449. 5950. 170 m. 60 37

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PLS PROTOTYPE Su. # 002 HIGH VOLTAGE MONITORS

DEC. COUNTS

L-Mode

		001115							3	.c. =	960 n	ns		
_		Reference	ce Counts				. 17							
_	, cep	+VL	+V ^U	Vollage		+VL	+V4	+VL	+ V4					
	0	054	166			53	173	52	173					
	1	173	239			172	243	172	243					
· -	2	243	038			243	41	243	42			·		
•	3	041	084			41	88	41	88					
_	4	088	126			87	129	87	124	·		·		
	5	130	165			129	168	129	168					
	6	169	202			168	205	167	205					
	7	206	238		· .	204	240	204	240			ŧ		
	8	238	015			239	18	239	18	-				
-	9	017	049			17	52	17	52					
	10	051	083			51.	85	51	85					
	-	084	116			اماكا	118	85	11.8					
	12	118	149			118	151	118	151					
	13	151	182			151	184	151	184					
	14	184	215			187	216	183	216					·
	15	216	248			216	249	216	249			·		
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PLS-PROTOTIFE SW # 00Z HIGH VOLTAGE MONITORS

DEC. COUNTS

Reference El-Mode

		Kefe	rence						300 1			
scep	Reference -VL	e Counts	-VL Voltage	-Vu								
0	048			-14.5							·	
1		121	-14.5	-19.3								
2	121		19.3	24.5								
3		170								-		-
4	170		30	36								
5		209								·		
6	208		42.4	49.3					·		·	
7		241							·			
8.	241		56.7	64.66			,					
9		014										
10	01.3		73.21	82.40								
1		039			,	-						
12	039		92.28	10251								
13		063										
14	063		114.31	126.56								·
15		086	126.56	139.74								
										·		
							_					
												•
-,												

4/22/77

E2-Mode mesmel DEC. COUNTS S.C. = 960 msMoacured Reference Counts :ep VoHge -Vu - V4 -VL -VL $-V_{\mathbf{L}}$ -V_U -Vu +VU -30 -10 56.70 92.28 139.74 203.02 287.41 399.94 . 550.00 75011 547 1016-97 1372.83 .1 1847.37 2480.18 1833 105ml 3324.05 4499.37 449.37 5950.0 4445 6025 150mm2 ATA Before AF CR us ん

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PLS-PROTOTYPE SHIGH VOLTAGE MONITORS

	DEC. COUNTS			Metal M-Mode					S.C. = 960 ms						
cep	Referen	ce Counts	Voltage	+4	tvu	+1/4									
26	051	057							 			-			
27	057	063													
28	063 .	069													
29	069	074													
30	075	080													
31	080	086	133.0	139.7											
32	086	091	139.7	146.7	144	137			:						
33	091	096	1447	153.9								1			
34	096	102				·									
35	102	107			·			·			1. 1				
36	107	112			·	·					·				
37	112	117			·	-									
38	117	122											 		
39	123	127													
40	128	132													
41	133	137		·			-								
42	138	142								:					
43	143	147	·	:				:		:	:				
44	147	152									:				
- 45	152	15.7									:				
46	157	162													
47	162	166													
48	167	171							·						
9	171	176													
50	176	180													
51	181	185													

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9/27/m 3

PLS-PROTOTIPE SW # 002 HIGH VOLTAGE MONITORS

4

		DEC CO	UNTS	Nezwa	ed.	M-M	lode	mul		S.	.c. =	960 m		4
	:ep	Referen	ce Counts	vollage		+VL	+Vn							
-	78	041	045	003		 							·	-
-	79	046	050											
•	80	050	054)		
•	81	054	058			 								-
-	82	058	062	<u> </u>										-
•	83	062	067				 	<u> </u>						-
-	84	067	071			 	ļ							-
-	85	071	075											-
-	86	075	079				<u> </u>							-
-	87	079	083				 						-	
_	88	084 [.]	088	· · ·										
-	,9	088	092								·			-
-	90	092	096			,								-
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	96	117	121	18424	1416.4	1929	1858		•					-
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	102	142	146											
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	DEC. CO	UNTS	Measu	red	M-M	lode							
Lep	Referen	ce Counts	Vollage		1VL	Wa							
104	150	154	1			 							-
105	154	158											
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116	199	203											
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126	240	244									-	·	
7	244	248	5738	5950	5799	6010							
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